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Information technology — Coded representation of immersive media —

Part 14:  
Scene description

Technologies de l'information — Représentation codée de média immersifs —

Partie 14: Description de scènes

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Foreword

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Introduction

This document defines the MPEG-I Scene Description. It provides an architecture for the MPEG-I Scene Description, a set of extensions based on ISO/IEC 12113, a set of APIs, and storage formats for scene description documents and scene description updates documents.

Information technology — Coded representation of immersive media —

Part 14:  
Scene description

# Scope

This document specifies extensions to existing scene description formats in order to support MPEG media, in particular immersive media. MPEG media includes but is not limited to media encoded with MPEG codecs, media stored in MPEG containers, MPEG media and application formats as well as media provided through MPEG delivery mechanisms. Extensions include scene description format syntax and semantics and the processing model when using these extensions by a Presentation Engine. It also defines a Media Access Function (MAF) API for communication between the Presentation Engine and the Media Access Function for these extensions. While the extensions defined in this document can be applicable to other scene description formats, they are provided for ISO/IEC 12113.

# Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO/IEC 12113, *Information technology — Runtime 3D asset delivery format — Khronos glTF™ 2.0*

ISO/IEC 14496-12, *Information technology — Coding of audio-visual objects — Part 12: ISO base media file format*

ISO/IEC 21778, *Information technology — The JSON data interchange syntax*

IEEE 754-2019, *IEEE Standard for Floating-Point Arithmetic*

IETF RFC 6902, *JavaScript Object Notation (JSON) Patch*

IETF RFC 8259, *The JavaScript Object Notation (JSON) Data Interchange Format*

ISO/IEC 23090-10,, Information technology — Coded representation of immersive media — Part 10: Carriage of visual volumetric video-based coding data

ISO/IEC DIS 23090-5/DAmd 1, Information technology – Coded Representation of Immersive Media – Part 5: Visual Volumetric Video-based Coding (V3C) and Video-based Point Cloud Compression (V-PCC)

ISO/IEC DIS 23090-12/DAmd.1, Information technology — Coded representation of immersive media — Part 12: MPEG immersive video — Amendment 1: V3C extension mechanism

Khronos, Vulkan 1.3.221 – A Specification (with all registered Vulkan extensions), <https://registry.khronos.org/vulkan/specs/1.3-extensions/html/vkspec.html>

# Terms, definitions, abbreviated terms, and conventions

## Terms and definitions

For the purposes of this document, the terms and definitions given in ISO/IEC 12113 and the following apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

ISO Online browsing platform: available at [https://www.iso.org/obp](https://www.iso.org/obp/ui)

IEC Electropedia: available at <https://www.electropedia.org/>

3.1.1

asset

3D scene described by a *scene description document* ([3.1.10](#Section_sec_3.1.10)) together with corresponding *scene description data* ([3.1.9](#Section_sec_3.1.9))

3.1.2

node

element in the *scene graph* ([3.1.12](#Section_sec_3.1.12))

3.1.3

media access function

function that retrieves and prepares media for rendering on request by the *presentation engine* ([3.1.7](#Section_sec_3.1.7))

3.1.4

media pipeline

chain of media processing components to process media

3.1.5

object

node in a *scene description document* ([3.1.10](#Section_sec_3.1.10))

3.1.6

patch document

document that contains update instructions

Note 1 to entry: For example, update instruction can be provided as defined in RFC 6902.

3.1.7

presentation engine

engine that processes and renders the *asset* ([3.1.1](#Section_sec_3.1.1))

3.1.8

scene activation time

time on the media timeline at which the scene described by a *scene description document* ([3.1.10](#Section_sec_3.1.10)) takes effect in the *presentation engine* ([3.1.7](#Section_sec_3.1.7))

3.1.9

scene description data

binary data that is described by *scene description document* ([3.1.10](#Section_sec_3.1.10))

3.1.10

scene description document

document describing a 3D scene

Note 1 to entry: For example, scene description document is containing description of node hierarchy, materials, cameras, as well as description information for meshes, animations, and other constructs.

3.1.11

scene description update

*patch document* ([3.1.6](#Section_sec_3.1.6)) to a *scene description document* ([3.1.10](#Section_sec_3.1.10)) or a *scene description document* ([3.1.10](#Section_sec_3.1.10))

3.1.12

scene graph

data structure used to represent *objects* ([3.1.5](#Section_sec_3.1.5)) in a 3D scene and their hierarchical relationships

3.1.13

timed accessor

accessor defined in ISO/IEC 12113 that has an MPEG\_accessor\_timed extension and is used to describe access to timed data

3.1.14

timed data

timed media

media, which when decoded results in content, possibly containing internal timing values, to be presented at a given presentation time and for a certain duration

## Abbreviated terms

|  |  |
| --- | --- |
| 3D | Three-Dimensional |
| 3DoF | Three Degrees of Freedom |
| 6DoF | Six Degrees of Freedom |
| API | Application Programming Interface |
| AR | Augmented Reality |
| DASH | Dynamic Adaptive Streaming over HTTP |
| dB | Decibel |
| DSR | Diffuse to Source Ratio |
| EOM | Enhanced Occupancy Mode |
| ERP | Equirectangular projection |
| glTF | Graphics Language Transmission Format |
| HOA | Higher Order Ambisonics |
| ISOBMFF | ISO Base Media File Format |
| JSON | JavaScript Object Notation |
| MAF | Media Access Function |
| MPEG | Moving Picture Experts Group |
| MIV | MPEG immersive video |
| IDL | Interface Definition Language |
| PCM | Pulse-Code Modulation |
| PLR | Point Local Reconstruction |
| RT60 | 60 dB Reverberation Time |
| SDP | Session Description Protocol |

## Conventions

### General

The mathematical operators used in this document are similar to those used in the C programming language. However, the results of integer division and arithmetic shift operations are defined more precisely, and additional operations are defined, such as exponentiation and real-valued division. Numbering and counting conventions generally begin from 0.

### Arithmetic operators

|  |  |
| --- | --- |
| + | addition |
| − | subtraction (as a two-argument operator) or negation (as a unary prefix operator) |
| \* | multiplication, including matrix multiplication |
| / | integer division with truncation of the result toward zero. For example, 7 / 4 and −7 / −4 are truncated to 1 and −7 / 4 and 7 / −4 are truncated to −1. |
| ÷ | division in mathematical equations where no truncation or rounding is intended. |

### Logical operators

|  |  |
| --- | --- |
| ! | Boolean logical "not". |

### Relational operators

|  |  |
| --- | --- |
| > | Greater than. |
| >= | Greater than or equal to. |
| < | Less than. |
| <= | Less than or equal to. |
| == | Equal to. |
| != | Not equal to. |

### Bit-wise operators

|  |  |
| --- | --- |
| ~ | bit-wise "not".  When operating on integer arguments, operates on a two's complement representation of the integer value. When operating on a binary argument that contains fewer bits than another argument, the shorter argument is extended by adding more significant bits equal to 0. |
| & | bit-wise "and".  When operating on integer arguments, operates on a two's complement representation of the integer value. When operating on a binary argument that contains fewer bits than another argument, the shorter argument is extended by adding more significant bits equal to 0. |
| | | bit-wise "or".  When operating on integer arguments, operates on a two's complement representation of the integer value. When operating on a binary argument that contains fewer bits than another argument, the shorter argument is extended by adding more significant bits equal to 0. |
| ^ | bit-wise "exclusive or".  When operating on integer arguments, operates on a two's complement representation of the integer value. When operating on a binary argument that contains fewer bits than another argument, the shorter argument is extended by adding more significant bits equal to 0. |
| x >> y | arithmetic right shift of a two's complement integer representation of x by y binary digits.  This function is defined only for non-negative integer values of y. Bits shifted into the MSBs as a result of the right shift have a value equal to the MSB of x prior to the shift operation. |
| x << y | arithmetic left shift of a two's complement integer representation of x by y binary digits.  This function is defined only for non-negative integer values of y. Bits shifted into the LSBs as a result of the left shift have a value equal to 0. |

### Assignment operators

|  |  |
| --- | --- |
| = | assignment operator. |
| ++ | increment, i.e. x++ is equivalent to x = x + 1; when used in an array index, evaluates to the value of the variable prior to the increment operation. |
| -- | decrement, i.e. x-- is equivalent to x = x − 1; when used in an array index, evaluates to the value of the variable prior to the decrement operation. |
| += | increment by amount specified, i.e. x += 3 is equivalent to x = x + 3, and x += (−3) is equivalent to x = x + (−3). |
| −= | decrement by amount specified, i.e. x −= 3 is equivalent to x = x − 3, and x −= (−3) is equivalent to x = x − (−3). |

### Other operators

|  |  |
| --- | --- |
| y..z | range operator/notation.  This function is defined only for integer values of y and z. When z is larger than or equal to y, it defines an ordered set of values from y to z in increments of 1. Otherwise, when z is smaller than y, the output of this function is an empty set. If this operator is used within the context of a loop, it specifies that any subsequent operations defined are performed using each element of this set, unless this set is empty. |

### Order of operation precedence

When order of precedence in an expression is not indicated explicitly by use of parentheses, the following rules apply:

Operations of a higher precedence are evaluated before any operation of a lower precedence.

Operations of the same precedence are evaluated sequentially from left to right.

[Table 1](#Table_tab_1) specifies the precedence of operations from highest to lowest; a higher position in the table indicates a higher precedence.

NOTE For those operators that are also used in the C programming language, the order of precedence used in this document is the same as used in the C programming language.

Table 1 — Operation precedence from highest (at top of table) to lowest (at bottom of table)

| **operations (with operands x, y, and z)** | |
| --- | --- |
| "x++", "x--" |  |
| "!x", "−x" (as a unary prefix operator) |  |
|  |  |
| "x \* y", "x / y", "x ÷ y", "x % y" |  |
| "x + y", "x − y" (as a two-argument operator) |  |
| "x << y", "x >> y" |  |
| "x < y", "x <= y", "x > y", "x >= y" |  |
| "x == y", "x != y" |  |
| "x & y" |  |
| "x | y" |  |
| "x && y" |  |
| "x || y" |  |
| "x ? y : z" |  |
| "x..y" |  |
| "x = y", "x += y", "x −= y" |  |

### Text description of logical operations

In the text, a statement of logical operations as would be described mathematically in the following form:

   if( condition 0 )  
      statement 0  
   else if( condition 1 )  
      statement 1  
   ...  
   else /\* informative remark on remaining condition \*/  
      statement n

* may be described in the following manner:
* ... as follows / ... the following applies:
* If condition 0, statement 0
* Otherwise, if condition 1, statement 1
* ...
* Otherwise (informative remark on remaining condition), statement n

Each "If ... Otherwise, if ... Otherwise, ..." statement in the text is introduced with "... as follows" or "... the following applies" immediately followed by "If ... ". The last condition of the "If ... Otherwise, if ... Otherwise, ..." is always an "Otherwise, ...". Interleaved "If ... Otherwise, if ... Otherwise, ..." statements can be identified by matching "... as follows" or "... the following applies" with the ending "Otherwise, ...".

In the text, a statement of logical operations as would be described mathematically in the following form:

   if( condition 0a && condition 0b )  
      statement 0  
   else if( condition 1a || condition 1b )  
      statement 1  
   ...  
   else  
      statement n

* may be described in the following manner:
* ... as follows / ... the following applies:
* If all of the following conditions are true, statement 0:

condition 0a

condition 0b

* Otherwise, if one or more of the following conditions are true, statement 1:

condition 1a

condition 1b

* ...
* Otherwise, statement n

In the text, a statement of logical operations as would be described mathematically in the following form:

if( condition 0 )

statement 0

if( condition 1 )

statement 1

may be described in the following manner:

When condition 0, statement 0

When condition 1, statement 1

In addition, a “continue” statement, which is used within loops, is defined as follows:

The “continue” statement, when encountered inside a loop, jumps to the beginning of the loop for the next iteration. This results in skipping the execution of subsequent statements inside the body of the loop for the current iteration. For example:

   for( j =0; j < N; j++ ) {  
     statement 0  
     if( condition 1 )  
         continue  
     statement 1  
     statement 2  
   }

is equivalent to the following:

   for( j =0; j < N; j++ ) {  
     statement 0  
     if( !condition 1 ) {  
        statement 1  
        statement 2  
     }  
   }

# Overview and architecture

## Overview

This document enables inclusion of timed media in a scene description. This is achieved through first defining features of a scene description that describe how to get the timed media, and second how a rendering process expects the data once it is decoded. In this version of the document, the features are defined as extensions to the glTF format defined in ISO/IEC 12113, see [Clause 5](#Section_sec_5).

In addition to the extensions, which provide an integration of timed media with the scene description, the document describes a reference scene description architecture that includes components such as Media Access Function, Presentation Engine, Buffer Control & Management, and Pipelines. To enable cross-platform/cross-vendor interoperability, the document defines Media Access Function (MAF) API and Buffer API, see [Clause 6](#Section_sec_6). The MAF API provides an interface between the Media Access Function and the Presentation Engine. The Buffer API is used to allocate and control buffers for the exchange of data between Media Access Function and Presentation Engine.

Not only the timed media described by the scene description may change over the time but also the scene description itself. The document defines how such change of a scene description document is signalled to the Presentation Engine.

Finally, a scene description may be stored, delivered, or extended in a way that is consistent with MPEG formats. The document defines a number of new features that allow a carriage utilizing ISO/IEC 14496-12 and its derived specifications, see [Clause 7](#Section_sec_7).

## Architecture

The scene description is consumed by a Presentation Engine to render a 3D scene to the viewer. The extensions defined in this document, allow for the creation of immersive experiences using timed media. The scene description extensions are designed with the goal of decoupling the Presentation Engine from the Media Access Function. Presentation Engine and Media Access Function communicate through the Media Access Function API, which allows the Presentation Engine to request timed media required for the rendering of the scene. The Media Access Function will retrieve the requested timed media and make it available in a timely manner and in a format that can be immediately processed by the Presentation Engine. For instance, a requested timed media asset may be compressed and residing in the network, so the Media Access Function will retrieve and decode the asset and pass the resulting decoded media data to the Presentation Engine for rendering. The decoded media data is passed in form of buffers from the Media Access Function to the Presentation Engine. The requests for timed media are passed through the Media Access Function API from the Presentation Engine to the Media Access Function.

[Figure 1](#Figure_fig_1) depicts the reference architecture.

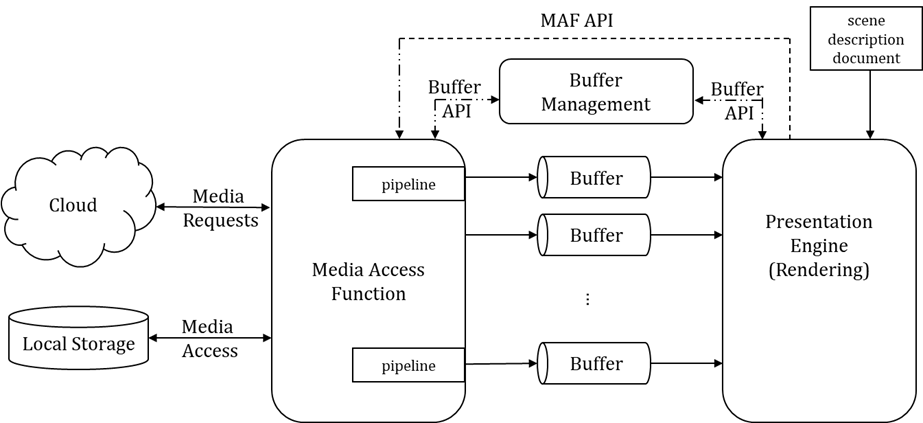


Figure 1 — Scene description reference architecture

The interfaces (MAF API, Buffer API) and extensions to ISO/IEC 12113 are within the scope of this document.

The following principles apply:

The format of the buffers shall be provided by the scene description document and shall be passed to the MAF through the Media Access Function API

Pipeline shall perform necessary transformations to match the buffer format and layout declared in the scene description for that buffer

The fetching of scene description document and scene description updates may be triggered by the MAF.

[Figure 1](#Figure_fig_1) depicts the reference architecture for scene description. The corresponding procedures are described as follows:

1. The Presentation Engine receives and parses the scene description document and following scene description updates
2. The Presentation Engine identifies timed media that needs to be presented and identifies the required presentation time
3. The Presentation Engine then uses the MAF API to request the media and provides the following information:
4. where the MAF can find the requested media
5. what parts of the media and at what level of detail
6. when the requested media has to be made available
7. in which format it wants the data and how it is passed to the Presentation Engine
8. The MAF instantiates the media fetching and decoding pipeline for the requested media at the appropriate time.
9. It ensures that the requested media is available at the appropriate time in the appropriate buffers for access by the Presentation Engine
10. It ensures that the media is decoded and reformatted to match the expected format by the Presentation Engine as described by the scene description document

The exchange of data (media and metadata) shall be done through buffers (circular and static buffers). The buffer management shall be controlled through the Buffer API. Each buffer should contain sufficient header information to describe its content and timing.

The information provided to the Media Access Function by the Presentation Engine allows it to

Select the appropriate source for the media (multiple could be specified) and the MAF may select based on preferences and capabilities. Capabilities may for example be decoding capabilities or supported formats. Preferences may for example be user settings.

For each selected source,

1. access the media by using a media access protocol.
2. setup the media pipeline to provide the information in the correct buffer format

The MAF may obtain additional information from the Presentation Engine in order to optimize the delivery, for example the required quality for each of the buffers, the exact timing information, etc.

The Media Access Function shall setup and manage the pipeline for each requested media or metadata. A pipeline takes as input one or more media or metadata tracks and outputs one or more buffers. The pipeline shall perform all the necessary processing, such as streaming, demultiplexing, decoding, decryption, and format conversion to match the expected buffer format. The final buffer or set of buffers are then used to exchange data with the Presentation Engine.

An example of pipelines setup is depicted in [Figure 2](#Figure_fig_2) for the case of a V-PCC compressed point cloud object that is referenced in the scene description. Pipeline #1 creates four video decoders and one patch data decoder. The pipeline is also responsible for processing this data and performing 3D reconstruction based on the received information. The reconstructed data is then fed to the final buffer that is accessed by the Presentation Engine. Pipeline #2 on the other hand is not performing the 3D reconstruction process and provides decoded raw data onto the buffers, which are accessed by the Presentation Engine.

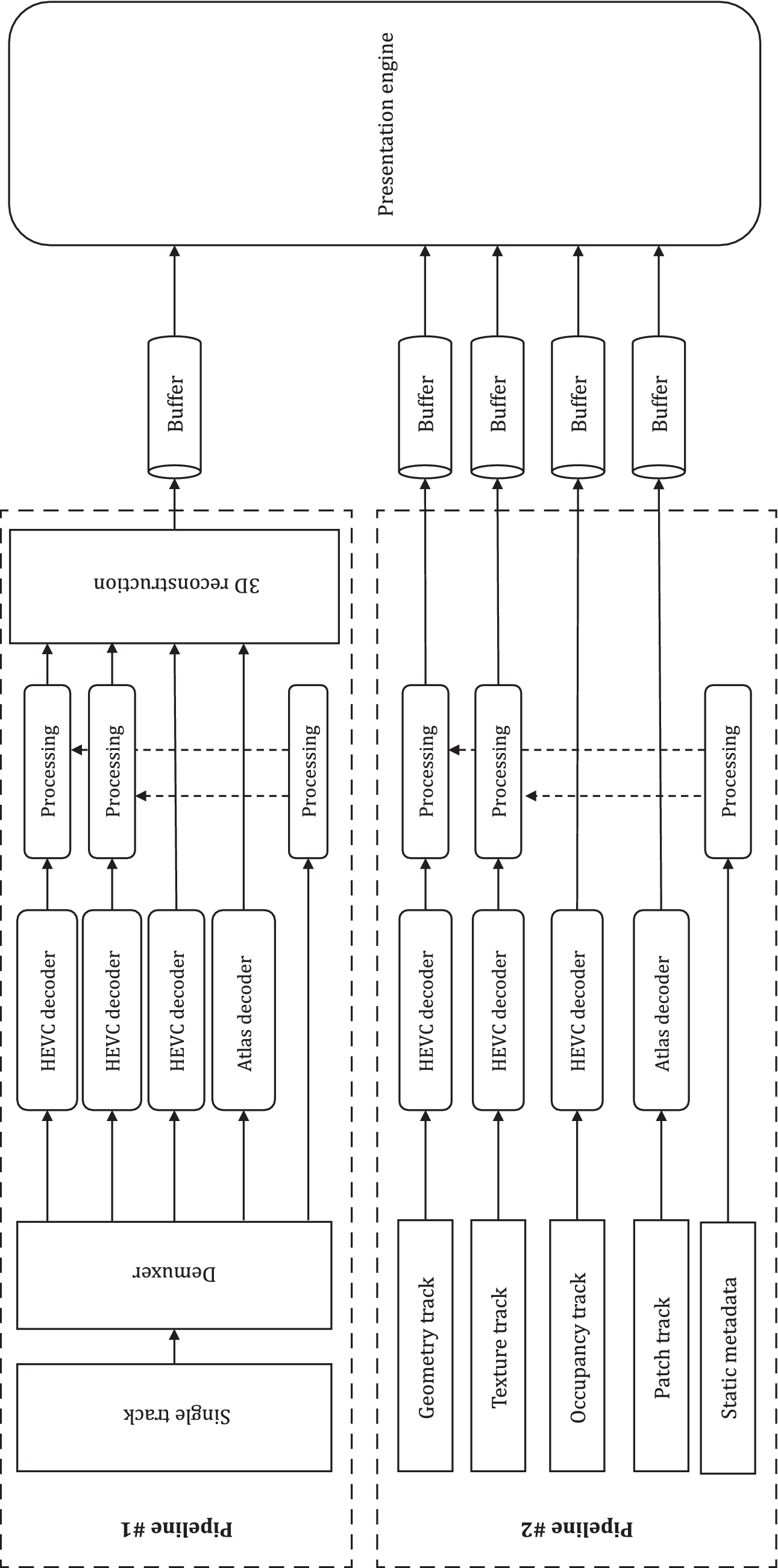


Figure 2 — An example of pipelines in scene description

## Timing model

A scene and all contained nodes share a global common presentation timeline. An initial glTF document is used as an entry point for consuming a 3D scene. The scene activation time of that document may be set externally or may be determined by the user and is considered the presentation time T0 of the 3D scene. Each media is started at time T0 + Tinit, where Tinit is equal to startTime, when present, or equal to the earliest time at which the media is available if autoplay is equal to true and autoplayGroup is not present, or the earliest time at which all media with the same autoplayGroup are available.

The first sample of each media consumed at T0 + Tinit is the one with presentation time equal to startTimeOffset. The media is consumed up to the sample with presentation time equal to the endTimeOffset, when present, or up to the last sample present in the media. When loop is set to true, at each loop the timeline is increased by adding the endTimeOffset – startTimeOffset, when endTimeOffset is present, or duration – startTimeOffset, when endTimeOffset is not present.

When a scene is updated through patch document to a scene description document or a scene description document, the media timeline remains unchanged and continues to be evaluated in respect to the T0, i.e. the activation time of the initial glTF document used as an entry point for consuming the 3D scene.

Animations described by the scene description document may be controlled (e.g., activated, paused, stopped) through MPEG\_animation\_timing extension. The activation timing of control events is identified by the timing of a sample in a metadata track. Once an animation event is activated the timeline of the animation is determined by animation data in the scene description data and the information provided by the animation sample in the metadata track (e.g., speed, start\_frame, end\_frame).

All static media of a scene are assumed to be presented at time T0. Timed media shall start at the indicated T0 + Tinit. An object that has timed media components, shall not be rendered until the indicated T0 + Tinit of these components. T0 + Tinit of all the timed media components of the same object shall be equal.

Any extensions that include new primitive attributes shall register the attributes in Annex B.

# Scene description extensions

## General

### Overview of extensions

An extension mechanism that allows to extend glTF 2.0 with new capabilities is defined in ISO/IEC 12113. A glTF node may have an optional extensions property that lists the extensions that are used by this node. All extensions that are used in a glTF document shall be listed in the top-level extensionsUsed array object, while extensions that are required to correctly load/render the scene shall also be listed in the extensionsRequired array.

A number of extensions, listed in [Table 2](#Table_tab_2), that enable support for timed media, are specified in [subclauses 5.2](#Section_sec_5.2), [5.3](#Section_sec_5.3), [5.4](#Section_sec_5.4), and [5.5](#Section_sec_5.5). Extensions can be defined under Vendor, EXT, KHR, or KHX namespaces. The extensions defined in this document are under the vendor-specific extension namespaces with an MPEG prefix. Examples of how to use the extensions are provided in [Annex F](#Annex_sec_F).

Table 2 — ISO/IEC 12113 extensions defined in this document

| **Extension Name** | **Brief Description** | **Type** | **Subclause** |
| --- | --- | --- | --- |
| MPEG\_media | Extension for referencing external media sources. | Generic | [5.2.1](#Section_sec_5.2.1) |
| MPEG\_accessor\_timed | An accessor extension to support timed media. | Generic | [5.2.2](#Section_sec_5.2.2) |
| MPEG\_buffer\_circular | A buffer extension to support circular buffers. | Generic | [5.2.3](#Section_sec_5.2.3) |
| MPEG\_scene\_dynamic | An extension to support dynamic scenes. | Generic | [5.2.4](#Section_sec_5.2.4) |
| MPEG\_texture\_video | A texture extension to support video textures. | Visual | [5.3.1](#Section_sec_5.3.1) |
| MPEG\_mesh\_linking | An extension to link two meshes and provide mapping information | Visual | [5.3.2](#Section_sec_5.3.2) |
| MPEG\_audio\_spatial | Adds support for spatial audio. | Audio | [5.4.1](#Section_sec_5.4.1) |
| MPEG\_viewport\_recommended | An extension to describe a recommended viewport. | Metadata | [5.5.1](#Section_sec_5.5.1) |
| MPEG\_animation\_timing | An extension to control animation timelines. | Metadata | [5.5.2](#Section_sec_5.5.2) |

[Figure 3](#Figure_fig_3) depicts the glTF 2.0 hierarchy that includes the extensions defined in this document.

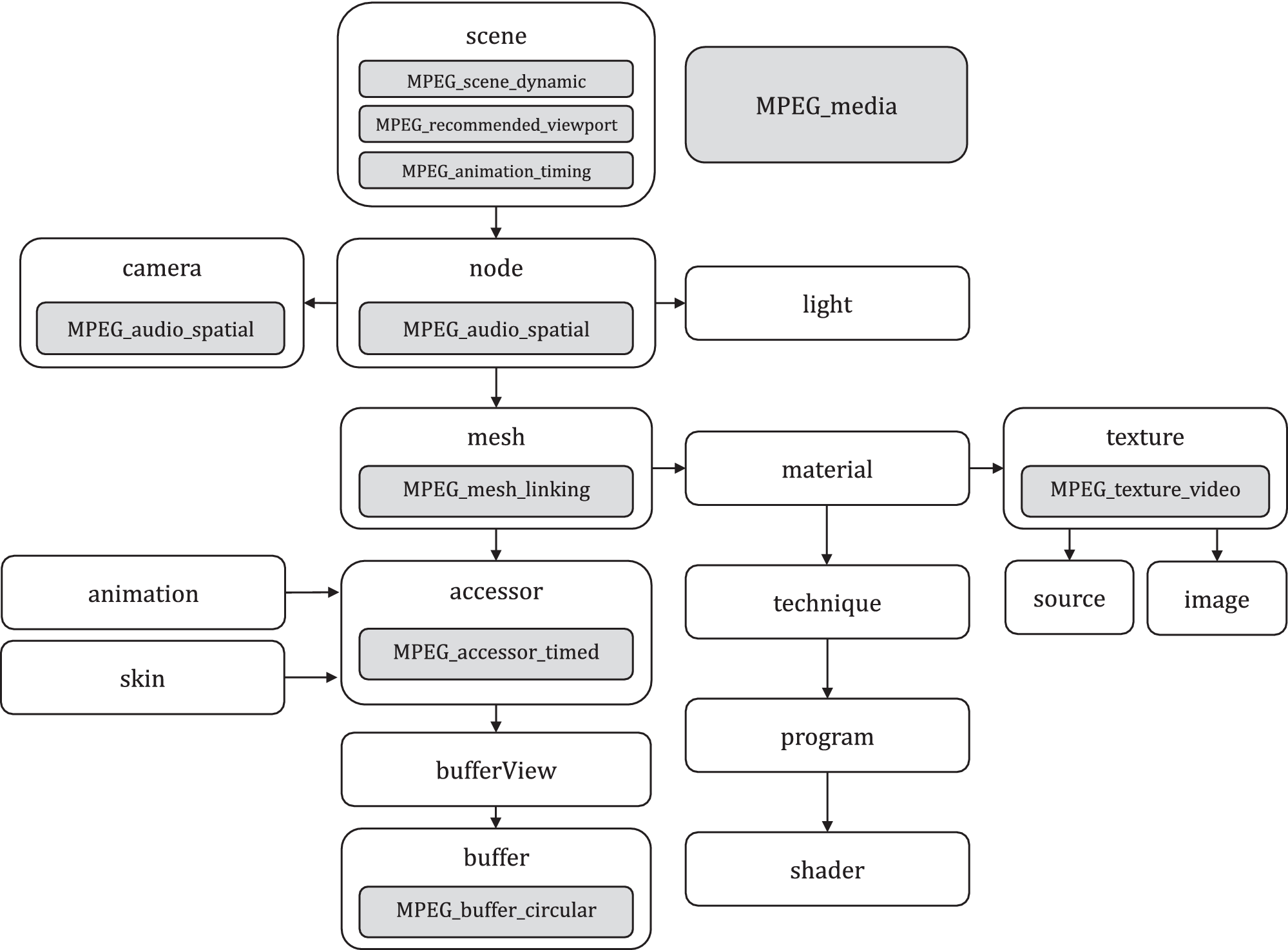


Figure 3 — An overview of the glTF document structure with MPEG extensions defined in this document

### Formatting and typing

For binary data fields the following applies. The read\_bits( n ) function reads the next n bits from the buffer data and advances the data pointer by n bit positions. When n is equal to 0, read\_bits( n ) is specified to return a value equal to 0 and to not advance the data pointer.

The following types specify the types and parsing process for binary data fields:

bits(n) fixed-pattern bit string using n bits written (from left to right) with the left bit first. The parsing process for this descriptor is specified by the return value of the function read\_bits( n )

bits(n)[m] array of m fixed-pattern bit strings with length of n bits.

uint(n) unsigned integer using n bits. The parsing process for this descriptor is specified by the return value of the function read\_bits( n ) interpreted as a binary representation of an unsigned integer with the most significant bit written first.

int(n) signed integer using n bits. The parsing process for this descriptor is specified by the return value of the function read\_bits( n ) interpreted as a two's complement integer representation with the most significant (left) bit written first. In particular, the parsing process for this type is specified as follows:

   int(n) {  
         value = read\_bits( n )  
         if( value < ( 1 << ( n – 1 ) ) )  
            return value  
         else  
            return ( value | ~( ( 1 << (n – 1)) – 1 ) )  
      }

float(n) binary floating point value using n bits. The parsing process for this descriptor is as specified in IEEE 754-2019.

For JSON data fields, the following type definitions apply:

number: primitive type defined in ISO/IEC 21778

string: primitive type defined in ISO/IEC 21778

boolean: primitive type defined in ISO/IEC 21778

array: structured type defined in ISO/IEC 21778

object: structured type defined in ISO/IEC 21778

## Generic extensions

### MPEG\_media extension

#### General

The MPEG media extension, identified by MPEG\_media, provides an array of media items referenced in a scene description document.

When present, the MPEG\_media extension shall be included as a top-level extension.

#### Semantics

The definition of all objects within MPEG\_media extension is provided in [Tables 3](#Table_tab_3) to [6](#Table_tab_6).

Table 3 — Definitions of top-level objects of MPEG\_media extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| media | array | N/A | M | An array of items that describe the external media, referenced in this scene description document. |

Table 4 — Definitions of item in the media array of MPEG\_media extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| name | string | N/A | O | The user-defined name of the media. |
| startTime | number | 0 | O | The startTime gives the time at which the rendering of the timed media will begin. The value is provided in seconds.  In the case of timed textures, the static image should be rendered as a texture until the startTime is reached. A startTime of 0 means the presentation time of the current scene.  Either startTime or autoplay shall be present in glTF description. |
| startTimeOffset | number | 0 | O | The startTimeOffset indicates the time offset into the source, starting from which the timed media shall be generated. The value is provided in seconds, where 0 corresponds to the start of the source. |
| endTimeOffset | number | N/A | O | The endTimeOffset indicates the end time offset into the source, up to which the timed media shall be generated. The value is provided in seconds. If not present, the endTimeOffset corresponds to the end of the source media. |
| autoplay | boolean | True | O | Specifies that the media will start playing as soon as it is ready.  Either startTime or autoplay shall be present for a media item description.  Rendering of all media for which the autoplay flag is set to True should happen simultaneously. |
| autoplayGroup | integer | N/A | O | All media that have the same autoplayGroup identifier shall start playing synchronously as soon as all autoplayGroup media are ready.  autoplayGroup is only allowed if autoplay is set to True. |
| loop | boolean | False | O | Specifies that the media will start over again, every time it is finished. The timestamp in the buffer shall be continuously increasing when the media source loops, i.e. the playback duration prior to looping shall be added to the media time after looping. |
| controls | boolean | False | O | Specifies that media controls should be displayed (such as a play/pause button etc). |
| alternatives | array | N/A | M | An array of items that indicate alternatives of the same media (e.g. different video codecs used)  NOTE: the client can select items (i.e. uri and track) included in alternatives depending on the client’s capability. |

Table 5 — Definitions of items in the alternatives array of MPEG\_media extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| mimeType | string | N/A | M | The media's MIME type.  The profiles parameter, as defined in IETF RFC 6381, may be included as a part of the mimeType to specify the profile of the media container. (e.g. the profiles parameter indicates the DASH profile when the uri specifies a DASH manifest) |
| uri | string | N/A | M | The uri of the media. Relative paths are relative to the .gltf file. If the reference media is a real-time media stream, then the uri shall follow the referencing scheme as specified in [Annex C](#Annex_sec_C). If the tracks element is present, the last part of the URI (i.e. the stream identifier such as the mid) is provided by the tracks information. |
| tracks | array | N/A | O | An array of items that lists the components of the referenced media source that are to be used. These can e.g. be a track number of an ISOBMFF, a DASH/CMAF SwitchingSet identifier, or a media id of an RTP stream. |
| extraParams | object | N/A | O | An object that may contain any additional media-specific parameters. |

Table 6 — Definitions of items in the tracks array of MPEG\_media.alternative extension

| **Name** | **Type** | **Default** | **Usage** | **Description** | |
| --- | --- | --- | --- | --- | --- |
| track | string | N/A | M | URL fragment to access the track within the media alternative.  The URL structure is defined for the following formats:  DASH: Using MPD Anchors (URL fragments) as defined in ISO/IEC 23009-1:2022, Annex C (Table C.1).  ISOBMFF: URL fragments as specified in ISO/IEC 14496-12:2022, Annex C.  SDP: stream identifier of the media stream as defined in [Annex C](#Annex_sec_C).  When V3C data is referenced in the scene description document as in item in MPEG\_media.alternative.tracks and the referenced item corresponds to an ISBOBMFF track, the following applies: | |
|  |  |  |  |  | * For single-track encapsulated V3C data, the referenced track in MPEG\_media shall be the V3C bitstream track. * For multi-track encapsulated V3C data, the referenced track in MPEG\_media shall be the V3C atlas track. |
| codecs | string | N/A | M | The codecs parameter, as defined in IETF RFC 6381, of the media included in the track.  When the track includes different types of codecs (e.g. the AdaptationSet includes Representations with different codecs), the codecs parameter may be signaled by comma-separated list of values of the codecs. | |

The JSON schema for the MPEG\_media extension is provided in [A.2](#Annex_sec_A.2).

#### Processing model

Processing of the MPEG\_media extension depends on the referenced media. In general, media in the MPEG\_media extension may be referenced by a circular buffer or by another extension defined in this document (e.g. MPEG\_scene\_dynamic). The Presentation Engine selects the media that is required at one of the available alternatives and is responsible for synchronization. The MAF instantiates the media fetching and two options exist. When the media in the MPEG\_media extension is referenced by a circular buffer, the processing pipeline instantiated by the MAF decodes the media and reformats it to match the expected format by the Presentation Engine. This processing may also require setting some information about the header information from the MPEG\_accessor\_timed as defined in [Table 8](#Table_tab_8) appropriately based on the data included in the media. This might depend on the reference media and information in the scene description document (e.g., information in the accessor pointing to the circular buffer). When the media in the MPEG\_media extension is referenced by another extension, the media is expected to be directly processed by the Presentation Engine.

### MPEG\_accessor\_timed extension

#### General

An accessor specified in ISO/IEC 12113 defines the types and layout of the data as stored in a buffer that is viewed through a bufferView. When timed media is accessed in a buffer, the data in the buffer is expected to change dynamically with time. Timed accessor extension allows to describe access to dynamically changing data used in scene. The timed accessor is an extension to regular accessors to indicate that the underlying data buffer is dynamic.

Timed accessors may have two bufferViews, one inherited from the containing accessor and the second in the MPEG\_accessor\_timed extension. The former shall be used to reference the timed media data. The latter, when present, shall point to the timed accessor information header. The absence of a bufferView inside the MPEG\_accessor\_timed extension shall indicate that no timed accessor information header is present in the buffer. When both bufferViews are present, they shall point to the same buffer element. Accessors that include the "MPEG\_accessor\_timed" extension shall only point to buffers that include the "MPEG\_buffer\_circular" extension.

The accessor.bufferView field, in an accessor that has the MPEG\_accessor\_timed extension, as well as the timed accessor information header fields apply to the data of each frame within the circular buffer.

The timed accessor extension is identified by MPEG\_accessor\_timed. When present, the MPEG\_accessor\_timed extension shall be included as extension of an accessor object defined in ISO/IEC 12113.

#### Semantics

The definition of all objects within MPEG\_accessor\_timed extension is provided in [**Table 7**](#Table_tab_7).

Table 7 — Definition of MPEG\_accessor\_timed extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| immutable | boolean | True | O | This flag equal to false indicates the accessor information componentType, type, and normalize may change over time. The changing values of componentType, type and normalize are provided through accessor information header.  This flag equal to true indicates the accessor information componentType, type, and normalize do not change over time and are not present in the accessor information header. |
| bufferView | integer | N/A | O | This property provides the index in the bufferViews array to a bufferView element that points to the timed accessor information header as described in [Table 8](#Table_tab_8). byteLength field of the bufferView element indicates the size of the timed accessor information header. The buffer properties in the bufferView element shall point to the same buffer as the bufferView in the containing accessor object.  In the absence of the bufferView attribute, it shall be assumed that the buffer has no dynamic header. In that case, the immutable flag shall be present and shall be set to True. |
| suggestedUpdateRate | number | 25.0 | O | The suggestedUpdateRate provides the frequency at which the Presentation Engine is recommended to poll the underlying buffer for new data. The rate is provided in number of changes per second. |

The timed accessor information header, when present, contains information required to properly access the media data in the buffer the accessor is pointing to. The timed accessor information header may change during the presentation of the scene. The timed accessor information header is provided as binary data as part of the buffer data and is accessible through the bufferView of the MPEG\_accessor\_timed extension.

[Table 8](#Table_tab_8) describes the syntax and semantics of the timed accessor information header.

Table 8 — Definition of timed accessor information header fields

|  |  |
| --- | --- |
| timed\_accessor\_information\_header() { | **Descriptor** |
| **timestamp\_delta** | f(32) |
| if (!immutable) { |  |
| **componentType** | u(32) |
| **type** | u(8) |
| **normalized** | u(1) |
| **reserved\_zero\_bit** | u(7) |
| } |  |
| **byteOffset** | u(32) |
| **count** | u(32) |
| **max** | size(componentType)\*  components |
| **min** | size(componentType)\*  components |
| **bufferViewByteOffset** | u(32) |
| **bufferViewByteLength** | u(32) |
| **bufferViewByteStride** | u(32) |
| } | u(32) |

**timestamp\_delta** - provides a delta in seconds that is added to the timestamp field of the corresponding buffer frame in the referenced buffer to determine the timestamp of the referenced timed media. When accessor information header is not present, the value of timestamp\_delta is inferred to be equal to 0. The sum of timestamp\_delta and the timestamp field of the corresponding buffer frame shall be smaller than the timestamp field of any other following buffer frame in the buffer.

**componentType -** corresponds to the accessor property componentType as defined in ISO/IEC 12113.

**type -** The field correspond to the accessor properties type as defined in ISO/IEC 12113 with following modification:

type equal to 0 indicates SCALAR as defined in ISO/IEC 12113.

type equal to 1 indicates VEC2 as defined in ISO/IEC 12113.

type equal to 2 indicates VEC3 as defined in ISO/IEC 12113.

type equal to 3 indicates VEC4 as defined in ISO/IEC 12113.

type equal to 4 indicates MAT2 as defined in ISO/IEC 12113.

type equal to 5 indicates MAT3 as defined in ISO/IEC 12113.

type equal to 6 indicates MAT4 as defined in ISO/IEC 12113.

**normalized -** corresponds to the accessor property normalized as defined in ISO/IEC 12113.

**reserved\_zero\_bit -** shall be equal to 0 in the timed accessor header information conforming to this version of this document. Other values are reserved for future use by ISO/IEC.

**byteOffset -** corresponds to the accessor property byteOffset as defined in ISO/IEC 12113.

**count -** corresponds to the accessor property count as defined in ISO/IEC 12113.

**max -** corresponds to the accessor property max as defined in ISO/IEC 12113. The max array sizes depend on the number of components as defined by the type defined in ISO/IEC 12113.

**min -** corresponds to the accessor property min as defined in ISO/IEC 12113. The min array sizes depend on the number of components as defined by the type defined in ISO/IEC 12113.

**bufferViewByteOffset -** corresponds to the bufferView property byteOffset defined in ISO/IEC 12113.

**bufferViewByteLength -** corresponds to the bufferView property byteLength defined in ISO/IEC 12113.

**bufferViewByteStride -** corresponds to the bufferView property byteStride fields defined in ISO/IEC 12113.The size( ) function returns the number of bits for a given componentType as defined by the Accessor Data Types table in ISO/IEC 12113.

The fields bufferViewByteOffset, bufferViewByteLength, and bufferViewByteStride update information of the bufferView referenced by the accessor containing the MPEG\_accessor\_timed extension and they provide a description of how to access the corresponding media data in the buffer.

The JSON schema for the MPEG\_accessor\_timed extension is provided in [A.3](#Annex_sec_A.3).

#### Processing model

For timed and dynamic data access, the MPEG\_accessor\_timed shall be used to describe access to the timed data. The Presentation Engine shall extract the information about the sample format from the accessor and, when present, the configuration of the header information from the MPEG\_accessor\_timed and pass it to the MAF. The MAF shall provide the information in the requested format in the buffers.

The timed accessor information header shall be present when at least some of the accessor information is dynamic. The presence of a timed accessor information header shall be signalled by the presence of the bufferView attribute in the MPEG\_accessor\_timed extension.

If present, the MAF shall insert the timed accessor information header prior to the corresponding data in the buffer frame. The offset, length, and stride of the data in the buffer frame may change from buffer frame to buffer frame and shall be signalled as part of the timed accessor information header.

A buffer shall not mix data from dynamic and static components, i.e. components that have a timed accessor information header and other components that do not have a timed accessor information header.

The Presentation Engine shall overwrite the accessor and buffer view information view that are described or referenced by an accessor that has the MPEG\_accessor\_timed extension, which itself includes a bufferView reference. In other words, the dynamic accessor and buffer view information take precedence over the static accessor and buffer view information present in the scene description.

### MPEG\_buffer\_circular extension

#### General

In order to support timed data access, the buffer element is extended to provide functionality of a circular buffer. The extension is named MPEG\_buffer\_circular and may be included as part of the "buffers" structures. Buffers that provide access to timed data shall include the MPEG\_buffer\_circular extension.

When MPEG\_buffer\_circular extension is present in a buffer element, the buffer element property uri shall not be present and the buffer element property byteLength shall indicate the maximum possible size of the buffer that may be needed to accommodate for the number of buffer frames indicated by count value.

When present, the MPEG\_buffer\_circular extension shall be included as extension of a buffer object defined in ISO/IEC 12113.

#### Semantics

The definition of all objects within MPEG\_buffer\_circular extension is provided in [Table 9](#Table_tab_9).

Table 9 — Definition of MPEG\_buffer\_circular extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| count | integer | 2 | O | The count field provides the recommended number of sequential buffer frames to be offered by a circular buffer to the presentation engine.  This information may be used by the MAF to setup the circular buffer towards the Presentation Engine. |
| media | integer | N/A | M | Index of the media entry in the MPEG\_media extension, which is used as the source for the input data to the buffer. |
| tracks | array | N/A | O | Index of a track of a media entry, indicated by media and listed by MPEG\_media extension, used as the source for the input data to this buffer.  When tracks element is not present, the media pipeline should perform the necessary processing of all tracks of the MPEG\_media entry, referenced by the media property, to generate the requested data format of the buffer.  When tracks array contains multiple tracks, the media pipeline should perform the necessary processing of all referenced tracks to generate the requested data format of the buffer. |
|  |  |  |  | If the track attribute is present and there are multiple "alternatives" (i.e. indicating equivalent content) in the referenced media, then the selected track shall be present in all alternatives.  NOTE: When more than one track is listed by tracks element, the corresponding buffer is in active state and the MAF is informed that the corresponding tracks are needed as source for the input buffer, then the MAF can optimize the delivery of multiple tracks. |

The JSON schema for the MPEG\_buffer\_circular is provided in [A.4](#Annex_sec_A.4).

#### Processing model

Frames of the buffer may differ in length based on the amount of data for each frame. A read and a write pointer are maintained for each circular buffer. By default, read and write access to the buffer will be served from the frame that is referenced by the read or write pointer respectively. Access to a particular frame index or timestamp should be supported.

The frames are read at the read pointer for rendering. New incoming frames from one or more media decoders are inserted at the write pointer. When present (i.e. when bufferView is included in the MPEG\_accessor\_timed extension of an accessor referencing this buffer) the timed accessor information header is included in the buffer frame as required, i.e. as indicated by the corresponding timed accessor. Prior data in that frame will be overwritten and the frame buffer should be resized accordingly.

[Figure 4](#Figure_fig_4) depicts the buffer structure:

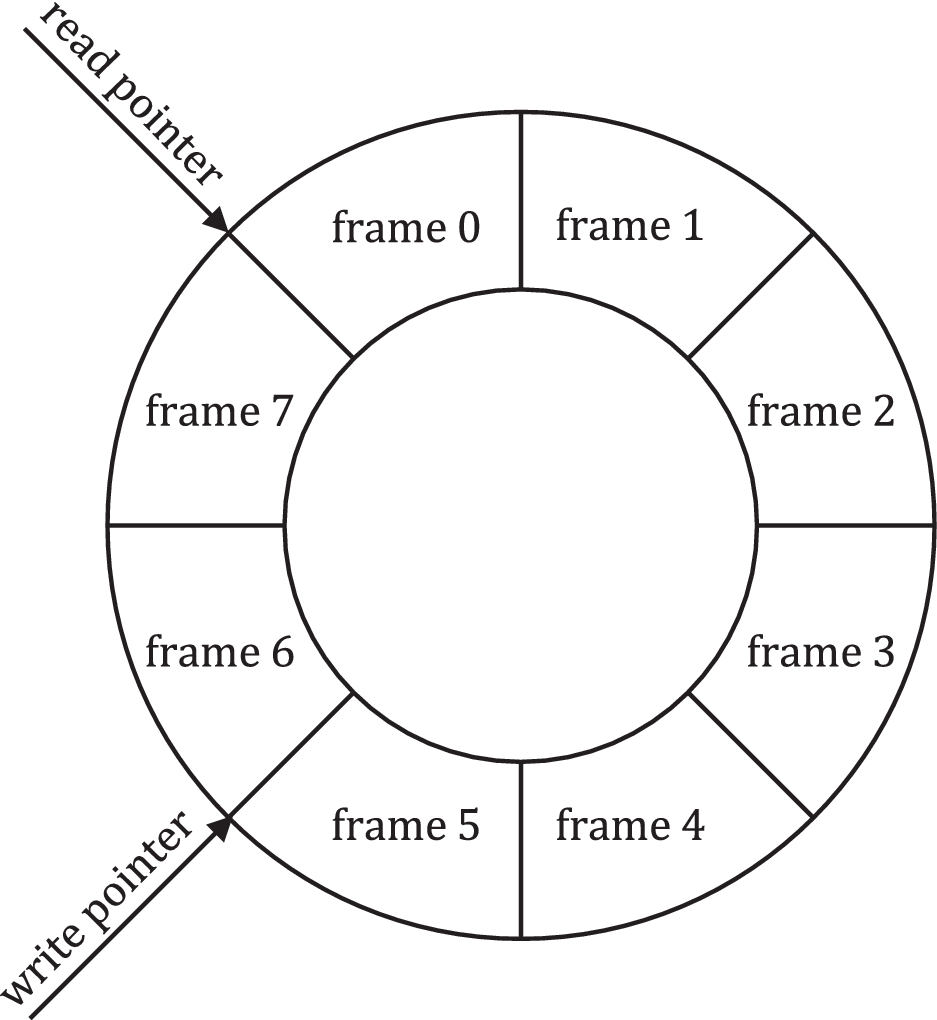


Figure 4 — An example of circular buffer operation with count value equal to 8

The buffer management ensures that Timestamp(write\_pointer) > Timestamp(read\_pointer) where Timestamp(pointer) is a function that returns the timestamp assigned to the buffer frame associated with that pointer. When overwriting existing data in a buffer frame with new data, the buffer management ensures that the read\_pointer is moved to a buffer frame with the earliest timestamp in the buffer. This may result in data drop but it ensures that no concurrent read and write access to the same buffer frame is performed.

### MPEG\_scene\_dynamic extensions

#### General

MPEG\_scene\_dynamic extension allows to indicate that the scene description document may be updated. MPEG\_scene\_dynamic extension points to MPEG\_media extension element that contains URL information to access scene document updates. For example, scene document updates may be provided as samples of a track or items as defined in [Clause 7](#Section_sec_7).

Scene updates shall be expressed as a scene description document or as a patch document using the JSON Patch protocol as defined in IETF RFC 6902. ISOBMFF-based carriage format for both scene description documents and patch documents using JSON patch protocol is specified in [subclause 7.2](#Section_sec_7.2). The glTF extensions MPEG\_media and MPEG\_scene\_dynamic shall be used in order to expose the dynamic scene updates, as described in [subclause 5.2.1](#Section_sec_5.2.1) and [5.2.4](#Section_sec_5.2.4).

After successfully performing an update operation, the resulting scene graph shall be consistent, i.e. syntactically valid and all references shall be correct. ISO/IEC 12113 uses the order of elements for referencing, therefore particular care should be used with update operations that change the order of elements in the graph, such as move and remove operations. The client shall update all references after every successful scene document update operation.

When a patch document contains update to nodes that does not match any node of the active scene document, the update command of this node shall be discarded.

When present, the MPEG\_scene\_dynamic extension shall be included as extension of a scene object defined in ISO/IEC 12113.

#### Semantics

The extension MPEG\_scene\_dynamic links to one of the entries listed in MPEG\_media. The definition of all objects within MPEG\_scene\_dynamic extension is provided in [Table 10](#Table_tab_10).

Table 10 — Definition of top-level objects of MPEG\_scene\_dynamic extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| media | integer | N/A | M | Provides the index of the media described in the MPEG\_media extension and which will contain the scene update data. |
| track | integer | N/A | O | Provides the index of a track of a media object, referenced by media attribute and listed by MPEG\_media extension. The track samples contain scene description updates and provide timing to perform these updates.  If track is not provided, it shall be assumed that all tracks provided by the referenced media object are used to provide the update samples. |

The JSON schema for the MPEG\_scene\_dynamic extension is provided in [A.5](#Annex_sec_A.5).

#### Processing model

The Presentation Engine parses the scene description document and maintains a representation of the scene graph in memory. The Presentation Engine receives scene description updates together with scene activation times. For example, the scene description updates can be provided as samples of an ISOBMFF track, as specified in [Clause 7](#Section_sec_7). In that case the scene activation time of a scene description update is indicated by the presentation time of the corresponding sample. When the sample becomes active, the Presentation Engine shall load the sample data and trigger the scene update to be performed. The scene description updates themselves modify the scene graph representation in memory and it can add new media to the scene. The timing for the newly added or updated media is determined by the metadata in the updated scene description document. If the scene description update contains an insertion of new glTF nodes and/or potential modifications to existing glTF nodes, the Presentation Engine should fetch any new content , e.g. using the MAF, associated with the scene description update and present the new content accordingly.

Each update operation shall either consist of a JSON Patch document for partial updates or a scene description document for a complete update. All update operations of a JSON Patch document shall be considered as a single timed transaction.

When a patch document contains update to nodes that does not match any node of active scene document, the update command of this node shall be discarded. When all update commands have been processed or discarded, the update operation shall be considered completed.

The fetching of updates and the activation of certain nodes may be triggered by different factors including the following:

Wallclock time

Presentation time

Interaction event

For live presentations, it is expected that presentation of the newly added glTF objects (e.g., new live media and potentially other dynamic objects) included in the scene during the scene updates will be synchronized with the scene presentation timeline via timing information (e.g., timestamps, etc.) included in the corresponding media formats and containers.

## Visual Extensions

### MPEG\_texture\_video extensions

#### General

MPEG texture video extension, identified by MPEG\_texture\_video, provides the possibility to link a texture object defined in ISO/IEC 12113 to a video source. The MPEG\_texture\_video extension provides a reference to the timed accessor, i.e. accessor with MPEG\_accessor\_timed extension, where the decoded timed texture will be made available.

When present, the MPEG\_texture\_video extension shall be included as extension of a textures object defined in ISO/IEC 12113.

When the MPEG\_texture\_video extension is not supported, the standard texture glTF element can be used as fallback.

NOTE When MPEG\_texture\_video extension is supported, the decoded video frames are used as textures starting from the time indicated in the corresponding MPEG\_media.media.startTime. If MPEG\_media.media.startTime is greater than 0, the static image frame indicated be texture.source element can be used until MPEG\_media.media.startTime.

#### Semantics

The definition of all objects within MPEG\_texture\_video extension is provided in [Table 11](#Table_tab_11).

Table 11 — Definition of top-level objects of MPEG\_texture\_video extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| accessor | integer | N/A | M | Provides a reference to the accessor, by specifying the accessor's index in accessors array, that describes the buffer where the decoded timed texture will be made available.  The accessor shall have the MPEG\_accessor\_timed extension.  The type, componentType, and count of the accessor depend on the width, height, and format. |
| width | integer | N/A | M | Provides the maximum width of the texture. |
| height | integer | N/A | M | Provides the maximum height of the texture. |
| format | string | RGB | O | Indicates the format of the pixel data for this video texture. The allowed values are: RED, GREEN, BLUE, RG, RGB, RGBA, BGR, BGRA, DEPTH\_COMPONENT. The semantics of these values are defined in Table 8.3 of OpenGL® a specification.[[2](#Reference_ref_8)]  Additionally, YCbCr formats are supported. The semantics for the YCbCr formats are defined in Table 76 in Vulkan specification [Vulkan 1.3]. A sampler with the MPEG\_sampler\_YCbCr extension shall be linked to a YCbCr texture.  Note that the number of components shall match the type indicated by the referenced accessor. Normalization of the pixel data shall be indicated by the normalized attribute of the accessor. |
| a OpenGL® is the trademark of a product supplied by Khronos. This information is given for the convenience of users of this document and does not constitute an endorsement by ISO of the product named. Equivalent products may be used if they can be shown to lead to the same results. | | | | |

The JSON schema for the MPEG\_texture\_video extension is provided in [A.6](#Annex_sec_A.6).

#### Processing model

When meshes, or any other element in scene description document, reference a texture element that contains MPEG\_texture\_video it gets the texture data provided in the buffer as described by the accessor indicated in the MPEG\_texture\_video extension. A new frame from the buffer should be read for each rendering cycle. If no new frame is available, the previous frame should be presented. The texture data stored into the buffer shall have the format indicated by the format attribute indicated by the MPEG\_texture\_video extension. When the picture size output by the media decoder are different from the size indicated by the width and height indicated by the MPEG\_texture\_video extension, two approaches are possible, when storing the decoded texture samples into the circular buffer. The first approach consists of storing the decoded texture samples into the buffer frames at the width and height indicated by the MPEG\_texture\_video extension. This requires that the size of the texture provided by the media decoder is reformatted, for example by MAF. The second approach consists of storing the decoded texture samples into the buffer frames at the width and height output by the decoder. In this case, the actual width and height of the picture shall be provided to the renderer, e.g. through the buffer frame header as specified in [Table 24](#Table_tab_24) if MAF is used.

NOTE Some implementations require the texture data stored within the buffer to have a static size as they cannot properly handle dynamically changing texture data formats. This requires the MAF or media decoders to generate the texture data at a static format and make it available at the buffers. On the other hand, other implementations can benefit of performing the size conversion by themselves in a more efficient manner and can cope with dynamically changing picture sizes in the underlying buffer. Derived specifications can mandate to operate in one of the two specified modes.

### MPEG\_mesh\_linking extensions

#### General

MPEG mesh linking extension, identified by MPEG\_mesh\_linking, provides the possibility to link a mesh to another mesh in a glTF asset.

The shadow mesh corresponds to regular mesh data as defined by ISO/IEC 12113 without the MPEG\_mesh\_linking extension. The dependent mesh can be transformed/animated by relying on the shadow mesh. The MPEG\_mesh\_linking extension included into the dependent mesh links the dependent mesh and the shadow mesh and provides with the data and information which is used to achieve the ability to animate the dependent mesh. Hence, the shadow mesh is present in the glTF assets to assist in achieving the ability to apply transformation onto the dependent mesh.

When present, the MPEG\_mesh\_linking extension shall be included as extension of a mesh object defined in ISO/IEC 12113.

When the MPEG\_mesh\_linking extension is not supported, the dependent mesh can be rendered as a regular timely updated mesh sequence of frames.

NOTE A reasonable backup when the extension is not understood is to render the dependent mesh without performing any animation. In such a case, the shadow mesh is not rendered and therefore is not added as a node in the scene.

#### Semantics

The definition of all objects within MPEG\_mesh\_linking extension is provided in [Table 12](#Table_tab_12).

Table 12 — Definition of top-level objects of MPEG\_mesh\_linking extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| correspondence | integer | N/A | M | Provides a reference to the accessor, by specifying the accessor's index in accessors array, that describe the buffer where the correspondence values between the dependent mesh and its associated shadow mesh will be made available.  The componentType of the referenced accessor shall be as indicated in [subclause 7.4](#Section_sec_7.4) and the type shall be SCALAR. |
| mesh | integer | N/A | M | Provides a reference to the shadow mesh, by specifying the mesh index in meshes array, associated to the dependent mesh for which the correspondence values are established. |
| pose | integer | N/A | M | Provides a reference to the accessor, by specifying the accessor's index in accessors array, that describe the buffer where the transformation of the nodes associated to the dependent mesh will be made available.  The componentType of the referenced accessor shall be FLOAT and the type shall be MAT4. |
| weights | integer | N/A | O | Provides a reference to the accessor, by specifying the accessor's index in accessors array, that describe the buffer where the “weights” to be applied to the morph targets of the shadow mesh associated to the dependent mesh will be made available.  The componentType of the referenced accessor shall be FLOAT and the type shall be SCALAR. |

The JSON schema for the MPEG\_mesh\_linking extension is provided in [A.7](#Annex_sec_A.7).

#### Processing model

The processing model could be as follows:

The corresponding shadow mesh for a dependent mesh is identified as provided by “mesh” in the MPEG\_mesh\_linking extension of the dependent mesh.

At runtime the Presentation Engine reads the corresponding frames from the circular buffers that the accessors with MPEG\_accessor\_timed extension point to as indicated by “correspondence”, “pose” and “weights”. The Presentation Engine glues each vertex of the dependent mesh to a face of the shadow mesh indicated by the correspondence value for the particular position and pose of the dependent mesh at that time instant. The render engine records the distance of each vertex of the dependent mesh to the plane of its corresponding shadow mesh face and records the position of the point onto which the vertex of the dependent mesh is projected within the associated face of the shadow mesh, i.e. the point within the face to which the distance is computed. With this parametrization between the two meshes, a transformation of the shadow mesh can directly be transferred to the dependent mesh.

The shadow mesh indicated as defined in ISO/IEC 12113 can transformed by means of using mesh primitives for skinning and pose-dependent morph targets.

The first step consists of linking the shadow mesh and the dependent mesh at the current pose of the dependent mesh. For this purpose, the shadow mesh is transformed to the same position and pose as the dependent mesh as provided by the data in the frames in the circular buffer corresponding to “pose” and “weights” in the MPEG\_mesh\_linking extension. This transformation is performed as any other transformation by means of using mesh primitives for skinning and pose-dependent morph targets. Then, the correspondence values for each of the vertices in the dependent mesh, as provided by the frames in the circular buffer corresponding to correspondences, indicating a mapping to a face of the shadow mesh is used to determine the relative location of each vertex in the dependent mesh to the associated face of the shadow mesh as explained above and in more detail in [Annex E](#Annex_sec_E).

With the relative locations representing the linked meshes, as a second step the shadow mesh at its original position and pose is transformed as indicated by animations. With the shadow mesh at the target position and pose, the dependent mesh is transformed by following the relative locations of each vertex with respect the associated faces of the shadow mesh, explained in more detail in [Annex E](#Annex_sec_E).

## Audio extensions

### MPEG\_audio\_spatial extensions

#### General

The MPEG audio extension adds support for spatial audio.

When present, the MPEG\_audio\_spatial extension shall be included as extension of a camera object, or a scene object defined in ISO/IEC 12113.

The MPEG\_audio\_spatial extension supports three different node types:

source: an audio source that provides input audio data into the scene. Mono objects and HOA sources (as defined in ISO/IEC 23008-3:2022, Annex F.1) are supported in this version of the document.

Type: 'Object' or 'HOA'

HOA audio sources shall ignore the parent node's position and be rendered only in 3DoF.

reverb: A reverb effect can be attached to the output of an audio source. Several reverb units can exist and sound sources can feed into one or more of these reverb units. An audio renderer that does not support reverb shall ignore it if the bypass attribute is set to true. If the bypass attribute is set to false, the audio renderer shall return an error message

listener: An audio listener represents the output of audio in the scene. A listener should be attached to a camera node in the scene. By being a child node of the camera, additional transformations can be applied to the audio listener relative to the transformation applied to the parent camera.

[Figure 5](#Figure_fig_5) depicts the processing chain for audio in a scene.

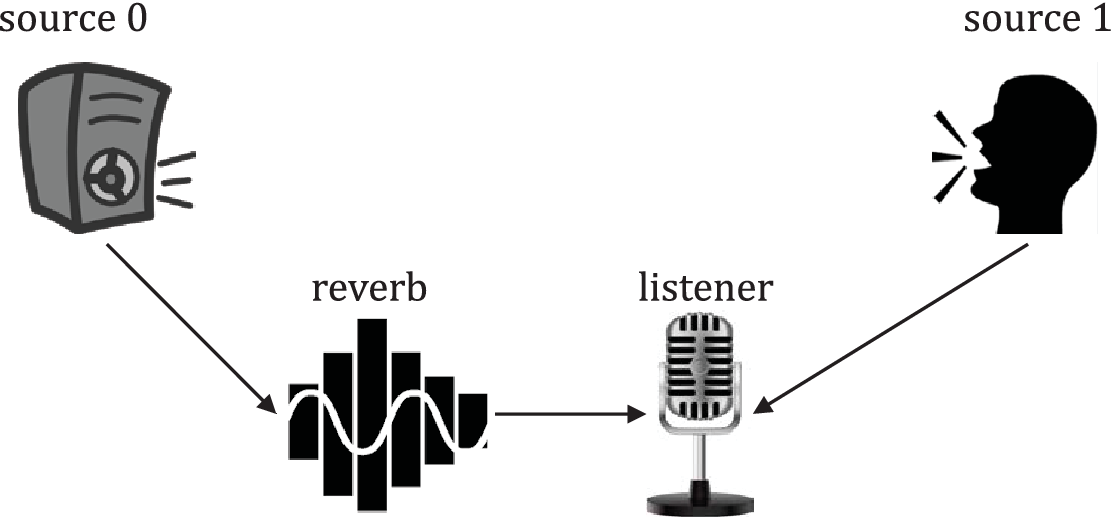


Figure 5 — An example of the processing chain for audio in a scene

The specification of any audio effect processing is outside the scope of this document.

The characteristics of a listener depend on the actual output devices available to the audio renderer.

#### Semantics

The definition of all objects within MPEG\_audio\_spatial extension is provided in [Tables 13](#Table_tab_13) to [17](#Table_tab_17).

Table 13 — Definition of top-level objects of MPEG\_audio\_spatial extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| sources | array | N/A | O | an array of source objects that are attached to the current node. |
| listener | object | N/A | O | a listener object that places an audio listener node in the scene that should be attached to a parent camera node. The audio listener characteristics depend on the available audio output devices. |
| reverbs | array | N/A | O | an array of reverb objects. |

Table 14 — Definition of source object of MPEG\_audio\_spatial.source extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| id | integer |  | M | unique identifier of the audio source in the scene. |
| type | string |  | M | Indicates the type of the audio source.  type value equal to “Object” indicates mono object  type value equal to “HOA” indicates HOA object |
| pregain | number | 0.0 | O | provides a level-adjustment in dB for the signal associated with the source. |
| playbackSpeed | number | 1.0 | O | defines the playback speed of the audio signal. A value of 1.0 corresponds to playback at normal speed. The value shall be between 0.5 and 2.0. |
| attenuation | enumeration | “linearDistance” | O | indicates the function used to calculate the attenuation of the audio signal based on the distance to the source.  attenuation value equal to "“noAttenuation" indicates no attenuation function should be used.  attenuation value equal to "inverseDistance" indicates inverse distance function should be used. |
|  |  |  |  | attenuation value equal to "linearDistance" indicates linear distance function should be used.  attenuation value equal to "exponentialDistance" indicates exponential distance function should be used.  attenuation value equal to "custom" indicates custom function should be used. The definition of custom function is outside of the scope of this document.  The attenuation functions and their parameters shall be as specified in [Annex D](#Annex_sec_D). |
| attenuationParameters | array | N/A | O | array of parameters that are input to the attenuation function. The semantics of these parameters depend on the attenuation function itself. |
| referenceDistance | number | 1.0 | O | provides the distance in meters for which the distance gain is implicitly included in the source signal after application of pregain.  When type equals ‘HOA’ the element shall not be present. |
| accessors | array | N/A | M | provides an array of accessor references, by specifying the accessors indices in accessors array, that describe the buffers where the decoded audio will be made available. |
| reverbFeed | array | N/A | O | provides one or more pointers to reverb units, optionally extended by a floating point scaling factor.  A reverb unit represents a reverberation audio processor that is configured by the metadata from a single reverb object. Typically, a reverb object represents reverberation properties of a single room. |
| reverbFeedGain | array | N/A | O | provides an array of gain [dB] values to be applied to the source’s signal(s) when feeding it to the corresponding reverbFeed.  The array shall have the same number of elements as the reverbFeed array field. |

Table 15 — Definition of listener objects of MPEG\_audio\_spatial.listener extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| id | integer | N/A | M | unique identifier of the audio listener in the scene. |

Table 16 — Definition of reverb object of MPEG\_audio\_spatial.reverb extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| id | integer | N/A | M | unique identifier of the audio reverb unit in the scene. |
| bypass | boolean | True | O | indicates if the reverb unit can be bypassed if the audio renderer does not support it. |
| properties | array |  | M | Array of items that contains reverbProperties objects describing reverb unit specific parameters |
| predelay | number | 0.0 | O | Delay [seconds] from onset of source to onset of late reverberation for which DSR is provided. |

Table 17 — Definition of reverbProperty object of MPEG\_audio\_spatial extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| frequency | number | N/A | M | Frequency for the provided RT60 and DSR values. |
| RT60 | number | N/A | M | RT60 values (in seconds) for the frequency provided in the ‘frequency’ field. |
| DSR | number | N/A | M | Diffuse-to-Source Ratio value [dB] for the frequency provided in the ‘frequency’ field. See explanatory text in [subclause 5.4.1.3](#Section_sec_5.4.1.3). |

The JSON schema for the MPEG\_audio\_spatial extension is provided in [A.8](#Annex_sec_A.8).

#### Processing model

The 60 dB reverberation time, short RT60, is defined as the time it takes for the sound pressure level in a room to reduce by 60 dB, measured after a generated steady-state test signal is abruptly ended. It is defined for a specific frequency as an attribute RT60 and specified in seconds.

The pre-delay time indicates the delay between the emission at the source and the onset of the diffuse late reverberation part of a signal (i.e. the sound after the early reflections) and is specified in seconds. It is frequency-independent.

The Diffuse-to-Source-Ratio (DSR) specifies the level of the diffuse reverberation relative to the level of the total emitted sound. This can be determined while making an RT60 measurement. It is defined for a specific <frequency> as an attribute DSR and can be computed when dividing the total diffuse reverb energy by the total emitted energy.

For example, a value of 0 indicates direct sound only, while large values will describe an almost completely reverberant (wet) acoustic environment. Note that the DSR values do not influence the amplitude of the direct sound in the process of rendering. While DSR is a general description of a room’s acoustic properties, rendering reverberation using DSR requires taking into account the source’s directivity pattern to find the total emitted energy from the PCM signal’s reference level. DSR values are independent of directivity and may be determined with a source of any directivity, e.g. an omni-directional source. The total diffuse reverb energy denotes the reverberation energy at any point in the region for which the acoustic environment is defined and is therefore directly linked to the PCM signal’s reference level.

## Metadata extensions

### MPEG\_viewport\_recommended extensions

#### General

Recommended viewport extension, identified by MPEG\_viewport\_recommended, provides dynamically changing recommended viewport information which includes translation and rotation as well as the intrinsic camera parameter of the camera object. The client may render the viewport according to the dynamically changing information.

When present, the MPEG\_viewport\_recommended extension shall be included as extension of a scene object defined in ISO/IEC 12113.

NOTE Another approach to achieve recommended viewport is to define an animation for a node with attached camera. The approach, however, does not support dynamically changing intrinsic camera and can only be defined during the creation of glTF object.

#### Semantics

The definition of all objects within MPEG\_viewport\_recommended extension is provided in [Table 18](#Table_tab_18).

Table 18 — Definition of MPEG\_viewport\_recommended extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| name | string | N/A | O | Label of the recommended viewport |
| translation | integer | N/A | O | Provides a reference to accessor where the timed data for the translation of camera object will be made available. The componentType of the referenced accessor shall be FLOAT and the type shall be VEC3, (x, y, z). |
| rotation | integer | N/A | O | Provides a reference to accessor where the timed data for the rotation of camera object will be made available. The componentType of the referenced accessor shall be FLOAT and the type shall be VEC4, as a unit quaternion, (x, y, z, w). |
| type | string | “perspective” | O | provides the type of camera. |
| parameters | integer | N/A | O | Provides a reference to a timed accessor where the timed data for the perspective or orthographic camera parameters will be made available. The componentType of the referenced accessor shall be FLOAT and the type shall be VEC4. |
|  |  |  |  | When the type of the camera object which includes this extension is perspective, FLOAT\_VEC4 means (aspectRatio, yfov, zfar, znear).  When orthographic type, FLOAT\_VEC4 means (xmag, ymag, zfar, znear).  The requirements on the camera parameters from ISO/IEC 12113 shall apply. |

The JSON schema for the MPEG\_viewport\_recommended extension is provided in [A.9](#Annex_sec_A.9).

#### Processing model

When a scene contains MPEG\_viewport\_recommended extension, renderer should manipulate camera object parameters and position based on data provided in the buffers described by the accessors indicated in the MPEG\_viewport\_recommended extension.

NOTE This document does not specify how the data is transmitted or made available at the respective circular buffers. A possible approach is that the MPEG\_media extension includes a media corresponding to a metadata track carrying the necessary information, which would be made available at the right format in the referenced timed accessors.

### MPEG\_animation\_timing extensions

#### General

Animation timing extension, identified by MPEG\_animation\_timing, enables alignment between media timelines and animation timelines defined by ISO/IEC 12113. Using the extension narrated stories can be created. The animation timing metadata allows simultaneous pausing and other manipulation of animations defined in ISO/IEC 12113 and timed media. By manipulating the global timeline for narrated content, the animation defined in ISO/IEC 12113 and timed media can be manipulated as well.

When present, the MPEG\_animation\_timing extension shall be included as extension of a scene object defined in ISO/IEC 12113.

#### Semantics

The definition of all objects within MPEG\_animation\_timing extension is provided in [Table 19](#Table_tab_19).

Table 19 — Definition of MPEG\_animation\_timing extension

| **Name** | **Type** | **Default** | **Usage** | **Description** |
| --- | --- | --- | --- | --- |
| accessor | integer | N/A | M | Provides a reference to the accessor, by specifying the accessor's index in accessors array, that describes the buffer where the animation timing data will be made available. The sample format shall be as defined in [subclause 7.6.3](#Section_sec_7.6.3).  The componentType of the referenced accessor shall be BYTE and the type shall be SCALAR. |

The JSON schema for the MPEG\_animation\_timing extension is provided in [A.10](#Annex_sec_A.10).

#### Processing model

When the MPEG\_animation\_timing extension is present in the scene description document, the Presentation Engine should adjust the glTF animation state based on the data provided in the buffer referenced by the accessor attribute of the MPEG\_animation\_timing extension.

# Media access function and buffer API

## General

Scene description document may be an entry point for an immersive media application. In such case the Presentation Engine receives the scene description document or a URL to a scene description document, which is downloaded.

The Presentation Engine parses the JSON-formatted scene description to build a scene graph in memory. It then iterates through all objects in the node and determines the associated media sources and their buffer formats and timing information.

The Presentation Engine then initializes the Media Access Function. For each attribute of each object, it requests the creation of a media pipeline for the processing of the corresponding media source. The Presentation Engine may choose either to pass a buffer handler for an existing circular buffer to the MAF or it may rely on the MAF to allocate the circular buffer.

The Presentation Engine then invokes the startFetching operation for the media pipeline ahead of the requested presentation time of the corresponding object.

The reference Media Access Function API and the Buffer API to create the media pipelines is provided in [subclauses 6.2](#Section_sec_6.2) and [6.3](#Section_sec_6.3), respectively. [Figure 6](#Figure_fig_6) shows a high-level overview of a typical processing procedure.

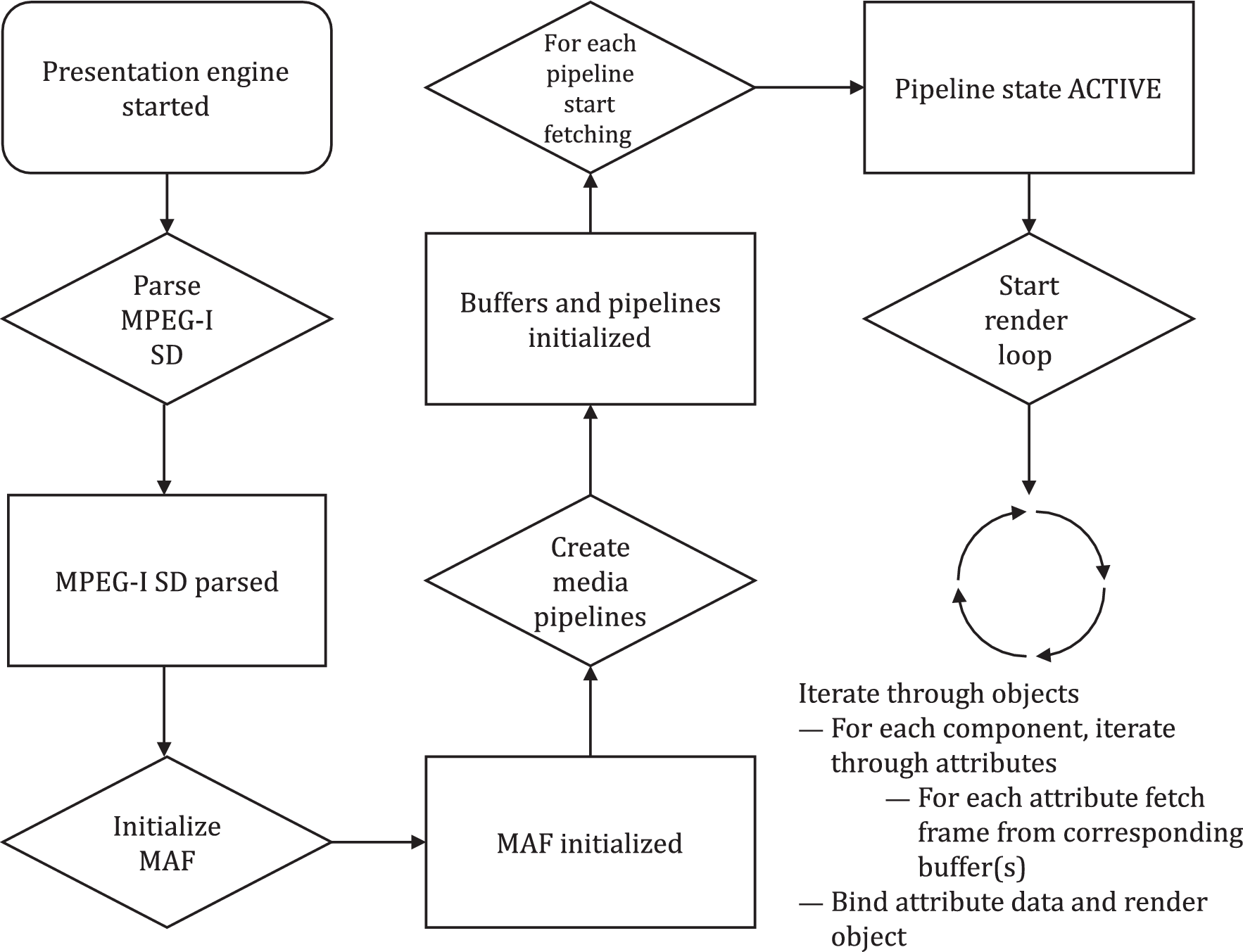


Figure 6 — High-level overview of a scene description processing procedure

## Media access function API

The MAF API is an API defined by this document. A Media Access Function as defined in this document shall support the MAF API to interface with the Presentation Engine.

The following methods are offered through API defined in [Table 20](#Table_tab_20).

Table 20 — Description of MAF API

| **Method** | **State after Success** | **Description** |
| --- | --- | --- |
| initialize( ) | READY | The Presentation Engine initializes a new media pipeline. It provides information related to the requested media or metadata. The MAF will setup the media pipeline and allocate the buffers, if they have not been allocated by the Presentation Engine. |
| startFetching( ) | ACTIVE | Once initialized and in READY state, the Presentation Engine may request the media pipeline to start fetching the requested data. |
| updateView() | ACTIVE | update the current view information. This function is called by the Presentation Engine to update the current view information, if the pose or object position have changed significantly enough to impact media access. It is not expected that every pose change will result in a call to this function. |
| stopFetching( ) | READY | The Presentation Engine may request to stop data fetching through this media pipeline. If subsequently, startFetching is called again, the stream fetching will resume from the current point, unless a start time is provided. |
| destroy( ) | IDLE | Finally, the Presentation Engine may request to destroy this media pipeline and free any associated resources. |

The pipeline interface defined using the IDL syntax specified in ISO/IEC 19516 is as follows:

interface Pipeline {  
   readonly attribute Buffer buffers[];  
   readonly attribute PipelineState state;  
   attribute EventHandler onstatechange;  
   void initialize(MediaInfo mediaInfo, BufferInfo bufferInfo[]);  
   void startFetching(TimeInfo timeInfo, ViewInfo viewInfo);  
   void updateView(ViewInfo viewInfo);  
   void stopFetching();  
   void destroy();  
};

The data types defined using the IDL syntax specified in ISO/IEC 19516 are as follows:

interface MediaInfo {  
   attribute String name;  
   attribute AlternativeLocation alternatives;  
};  
   
interface AlternativeLocation {  
   attribute String mimeType;  
   attribute Track tracks[];  
   attribute uri;  
};  
   
interface Track {  
   attribute String track;  
   attribute integer id;  
   attribute integer bufferId;  
};  
   
interface TimeInfo {  
   attribute double startTime;  
   attribute double timeOffset;  
   attribute boolean autoplay;  
   attribute boolean loop;  
};  
   
interface BufferInfo {  
   attribute integer bufferId;  
   attribute BufferHandle handle;  
   attribute unsigned long componentType;  
   attribute SampleType type;  
   attribute integer offset;  
   attribute integer stride;  
   attribute AttributeType attributeType;  
};  
   
interface ViewInfo {  
   attribute Pose pose;  
   attribute Camera camera;  
   attribute Transform objectTransform;  
};  
   
interface Pose {  
   attribute Position position  
   attribute Quaternion orientation;  
};  
   
interface Camera {  
   readonly attribute CameraProjectionType type;  
   readonly attribute PerspectiveCameraViewingVolume;  
   readonly attribute OrthographicCameraViewingVolume;  
   readonly attribute double zNear;  
   readonly attribute double zFar;  
};  
   
enum CameraProjectionType {"PERSPECTIVE", "ORTHOGRAPHIC"};  
   
interface PerspectiveCameraViewingVolume {  
   double aspectRatio;  
   double yFov;  
};  
   
interface OrthographicCameraViewingVolume {  
   double xmag;  
   double ymag;  
};  
   
typedef Transform float[4][4];  
   
typedef SampleType {"SCALAR", "VEC2", "VEC3", "VEC4", "MAT2", "MAT3", "MAT4"};  
   
enum AttributeType {"ATTRIB\_NORMAL","ATTRIB\_POSITION","ATTRIB\_COLOR", "ATTRIB\_TEXCOORD","ATTRIB\_INDEX","ATTRIB\_TANGENT", "ATTRIB\_WEIGHTS", "ATTRIB\_JOINTS"}

Semantics of componentType and type corresponds to the semantics of accessor properties componentType and type, respectively, defined in ISO/IEC 12113.

[Table 21](#Table_tab_21) provides semantics for the defined interfaces and their parameters:

Table 21 — API Structure and Parameter Semantics

| **Parameter Name** | **Description** |
| --- | --- |
| Pipeline | Provides a representation of a media pipeline that stores its current pipeline state PipelineState and keeps track of the output buffers of that pipeline.  The PipelineState may be IDLE, READY, ACTIVE, or ERROR. A pipeline in IDLE state means it has not been initialized yet. The READY state indicates that the pipeline has been initialized and is ready to start fetching media. When in ACTIVE state, the pipeline is actively fetching media. The ERROR state indicates that the pipeline has encountered an error that stopped the media access.  The EventHandler holds a pointer to a callback function, which will be called upon a change in the PipelineState. |
| MediaInfo | The MediaInfo carries information about the location of the media that the pipeline is to access. The MediaInfo carries the same information as provided by the MPEG\_media extension. A MediaInfo maybe assigned a name. It has to provide at least one location in the alternatives array. Each alternative contains a MIME type, a set of tracks, and the URI that can be used to access the media in that alternative.  The tracks indicate which streams/tracks/representations from the referenced media alternative are to be accessed by this pipeline. If none is specified, it shall be assumed that all components of the referenced media alternative are to be accessed. |
| TimeInfo | The TimeInfo indicates the time point at which the media is to be accessed and when to start the media access. The semantics of each field is identical to that provided in the MPEG\_media extension. |
| BufferInfo | The BufferInfo provides information about the expected format of the output buffer of the media pipeline.  The buffer may be allocated by the MAF or by the Presentation Engine. The handler is used to read or pass a reference to an allocated buffer. If allocated by the MAF, then only read access shall be allowed. If the pipeline is initialized without a valid buffer handler, then the MAF shall allocate the buffer.  the buffer format information in componentType, type, offset, and stride shall correspond to componentType, type, offset, stride in the corresponding accessor and bufferView.  The attributeType shall correspond to the corresponding primitive attribute.  The BufferHandle holds a handle for a buffer, which can be used to access the buffer. |
| ViewInfo | The ViewInfo represents the current positions of the object for which the media is accessed and the viewer’s pose. This information is useful to adjust the media access to the visibility of the object. For example, a far object may be accessed at a lower Level of Detail (LoD).  The ViewInfo.pose contains the pose information of the viewer, provided as a position and oritentation.  ViewInfo.camera provides also the intrinsic properties of the camera used by the Presentation Engine. The information about the intrinsic properties includes the type of camera projection. (e.g., perspective, orthographic, etc.) and related parameters. A camera may have intrinsic parameters such as distance to near and far clipping planes, aspect ratio, y-FoV (for perspective projection camera), and width and height of the viewing volume (for orthographic projection camera).  The ViewInfo.objectTransform contains the position and orientation of the object as a transform (a 4x4 matrix as defined by ISO/IEC 12113). All information shall use the scene’s coordinate system. |

The MAF may use the ViewInfo to optimize the streaming of the requested media, e.g. by adjusting the level of detail (number of polygons/points, texture resolution etc.) based on the distance to and orientation of the viewer. The BufferInfo contains information about each Buffer and describes the format of the samples and frames that are stored in that buffer. One or more tracks from the MediaInfo may feed into the same buffer. The link between the track that provides the actual media and the buffer that will store the output of the media pipeline is established through the bufferId attribute.

## Buffer API

The Buffer API is used by the Presentation Engine and the MAF to allocate and control buffers for the exchange of data between the Presentation Engine and the MAF through media pipelines.

The Buffer API offers the methods indicated in [Table 22](#Table_tab_22).

Table 22 — Description of buffer API

| **Method** | **Description** |
| --- | --- |
| allocate() | Allocates a buffer for the data exchange between the MAF and the Presentation Engine. |
| writeFrame() | writes a frame to the buffer. The write pointer moves to the next frame. |
| readFrame() | reads a frame from the buffer. If no timestamp is provided, the buffer pointer moves to the next frame. Otherwise, the read pointer remains unchanged. If the buffer is empty, an error is returned.  Prior frames may still be accessed using their timestamp as long as they are not overwritten. |
| free() | Destroys the buffers and frees any resources associated with it. |

When allocating a buffer, sufficient information is provided about the buffer configuration. This includes the maximum size of the buffer, the static information in the buffer header, the number of frames in the buffer for circular buffers, and the update rate of the buffer.

The Buffer API interface defined using the IDL syntax specified in ISO/IEC 19516 is as follows:

interface CircularBuffer {  
   readonly attribute Frame frames[];  
   readonly attribute count;  
   readonly attribute integer read\_idx;  
   readonly attributre integer write\_idx;  
   attribute integer headerLength;  
   attribute EventHandler onframewrite;  
   attribute EventHandler onframeread;  
   void allocate(int count);  
   void writeFrame(Frame frame);  
   Frame readFrame(optional double timestamp);  
   void free();  
};  
   
interface Frame {  
   attribute integer index;  
   attribute double timestamp;  
   attribute integer length;  
   attribute octet[length] data;  
};

[Table 23](#Table_tab_23) provides semantics for the defined interfaces and their parameters:

Table 23 — API structure and parameter semantics

| **Parameter Name** | **Description** |
| --- | --- |
| count | The number of frames contained in this circular buffer.  Each frame of the buffer will hold data at a particular time instance and will be identified by an index in the range of [0, count-1]. The index, timestamp and length of the frame are signaled as the frame metadata. |
| read\_idx | The index of the frame that can be read. If the read\_idx is equal to the write\_idx, then it shall be assumed that there is currently no frame available to be read. |
| write\_idx | The index of the frame at which a write operation can be performed. |
| headerLength | This provides the length in bytes of the buffer frame header that is available at the start of every frame in the buffer as specified in [Table 24](#Table_tab_24). A headerLength of 0 indicates that there is no buffer header.  When the buffer API is used, the buffer frame header shall not be present as part of the buffer frame data. For implementations that do not use the Buffer API, the buffer frame header information may be provided as part of the buffer frame data. |
| Frame | provides information about a frame in the buffer. The index is the position of the frame in the buffer. The timestamp corresponds to its presentation timestamp. The length corresponds to the length of the buffer.  The semantics of the Buffer Frame fields are provided in [Table 24](#Table_tab_24).  Note that the timestamp format is inherited from the accessed media and as such can be an NTP timestamp, a 0-offset timestamp, or any other format. |

Table 24 — Syntax and semantics of the buffer frame header

| **Syntax** | | **Length (bits)** | **Type** | **Semantics** |
| --- | --- | --- | --- | --- |
| index | | 8 | uint(8) | The index of the current buffer frame. The index is a value between 0 and count -1. |
| timestamp | | 64 | uint(64) | Provides the base timestamp of the data that is contained in this buffer frame. Together with the timestamp\_delta in the timed accessor information header, when present, it provides the timestamp of the data within the buffer frame. The 32 most significant bits represent the seconds part and the 32 least significant bits represent the fraction of a second part.  The timestamp field is not necessarily a wallclock time and the interpretation of this field is left to the Presentation Engine. |
| length | | 32 | uint(32) | The length of the data of this buffer frame, including the accessor information header fields defined in [Table 8](#Table_tab_8). |
| extra\_frame\_info\_flags | | 8 | uint(8) | A set of flags that indicate additional information related to this buffer frame. |
| if (extra\_frame\_info\_flags & 0X01 == 1) | |  |  | If the dimensions flag is set, then the buffer frame contains texture data and the related width and hight parameters are provided. |
|  | width | 32 | uint(32) | The width of any texture data stored within the buffer frame |
|  | height | 32 | uint(32) | The height of any texture data stored within the buffer frame |

# Carriage formats

## General

[Clause 7](#Section_sec_7) describes the carriage formats related to scene description. The scene description documents and scene description updates may be stored as samples of a track in ISOBMFF as defined in [subclause 7.2](#Section_sec_7.2), or as items as defined in [subclause 7.3](#Section_sec_7.3). Carriage for a mesh correspondence, pose and weights that are utilized by MPEG\_mesh\_linking extension is defined in [subclauses 7.4](#Section_sec_7.4) and [7.5](#Section_sec_7.5). Carriage for an animation timing, that is utilized by MPEG\_animation\_timing extension, is defined in [subclause 7.6](#Section_sec_7.6).

[Figure 7](#Figure_fig_7) shows an example relationship between items and tracks stored as one file. In the example JSON glTF file and a file representing glTF binary buffer are stored as items of a single file. The same file also contains tracks that can be reference from glTF file using the extensions defined in this document, such as MPEG\_media, MPEG\_buffer\_cirrcular and MPEG\_scene\_dynamic.

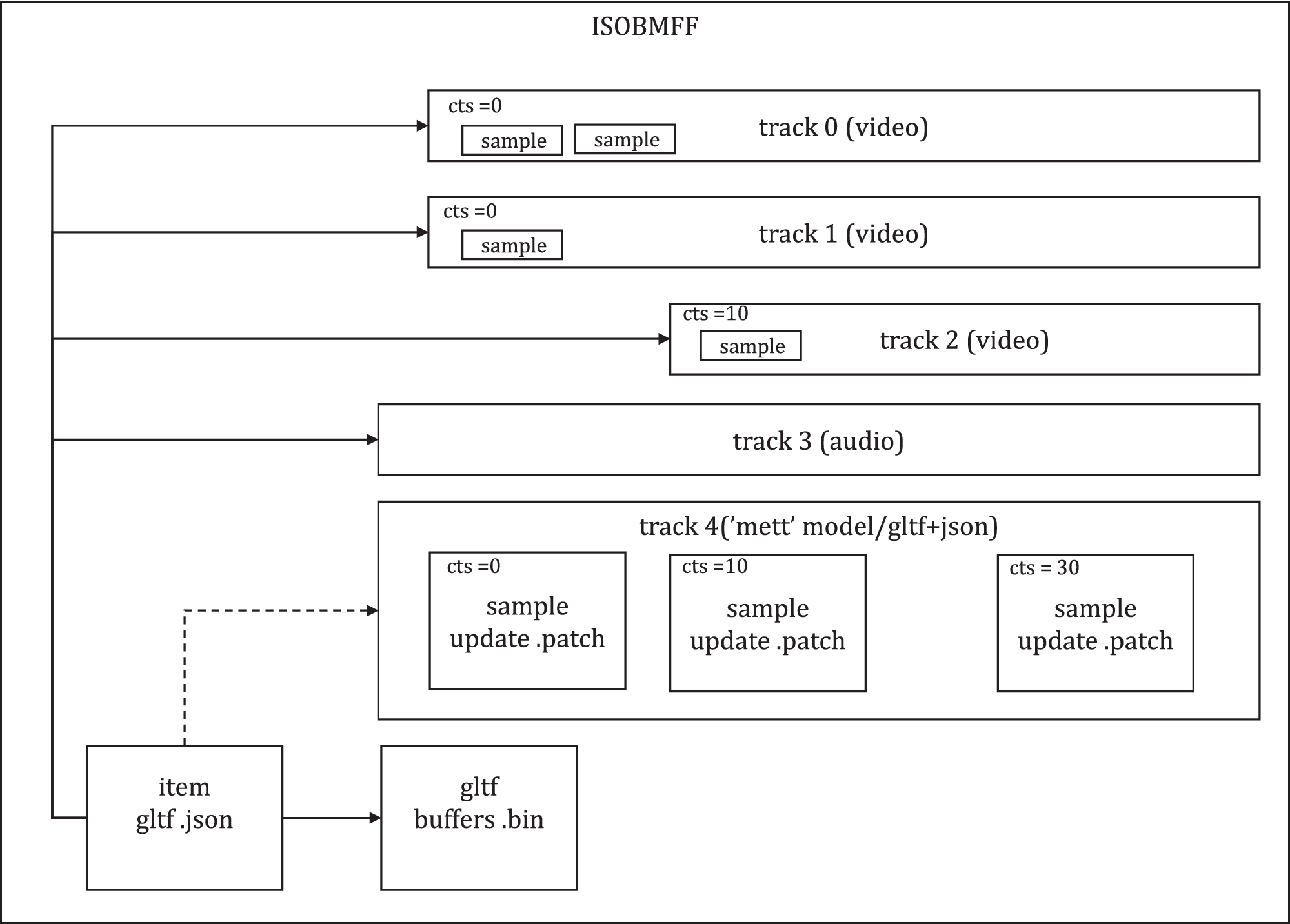


Figure 7 — Data relationship between the glTF .json stored as item and patch updates as a track.

## Carriage format for glTF JSON and JSON patch

### General

A track with samples containing glTF JSON documents and JSON patch document shall be stored as metadata media defined in ISO/IEC 14496-12 and shall fulfil the following condition:

'**meta**' handler type shall be used in the **HandlerBox** of the **MediaBox**.

The sample entry format shall be '**mett**' and:

**mime\_format** field shall be set to model/gltf+json,

**content\_encoding** field when present shall contain either an empty string or a value allowed in HTTP's Content-Encoding header.

**GLTFPatchConfigBox** may be present in the sample entry.

Samples containing glTF JSON documents shall be marked as a sync sample and shall use UTF-8 encoding as defined in IETF RFC 8259

Samples containing JSON patch documents shall not be marked as sync sample and shall use UTF-8 encoding as defined in IETF RFC 8259

Samples may have the **sample\_has\_redundancy** flag set to 1, in which case processing is applied as discussed in [subclause 7.7](#Section_sec_7.7).

The presentation time of a sample identifies the scene activation time for scene resulting from loading glTF JSON document or resulting from applying the JSON patch document contained in the sample as indicated by update\_mode in the GLTFPatchConfigBox to the active scene description document. When the GLTFPatchConfigBox is not present non-sync samples shall be applied as specified by update\_mode equal to 0.

NOTE The update of the scene description document as well as the fetching of the assets of possible new nodes to be rendered are expected to take place sufficiently ahead of time so that the presentation of the scene can continue without interruption.

### glTF patch config box

#### Definition

|  |  |
| --- | --- |
| Box Type: | 'glTC' |
| Container: | Sample Entry ('mett') |
| Mandatory: | No |
| Quantity: | 0 or 1 |

The glTF configuration box provides information how to process the samples of tracks with samples contain glTF JSON documents and JSON patch documents.

#### Syntax

class GLTFPatchConfigBox() extends Fullbox ('gltC', 0, 0) {  
   unsigned int(3) update\_mode;  
   unsigned int(5) reserved;  
}

#### Semantics

**update\_mode** specifies how to determine the target file associated with the patch documents contained in the non-sync samples of the track. When update\_mode is set to 0, the patch document contained in a non-sync sample of the track is to be applied to the glTF JSON document obtained by the processing of the previous sample (sync or non-sync) in decoding order, if any, or to the original glTF file including the metadata track into the MPEG\_media extensions (e.g., glTF Object as non-timed item). When update\_mode is set to 1, the patch document contained in a non-sync sample is to be applied to the glTF JSON document contained in the previous sync sample in decoding order, if any, or to the original glTF file including the metadata track into the MPEG\_media extensions (glTF Object as non-timed item). Values from 2 to 7 are reserved for future use.

## Carriage format for glTF object and glTF source object as non-timed item

### General

glTF can be stored as items, when there is no specific time associated to the loading of that resource or when the track storage is not appropriate. As defined in ISOBMFF, items are declared in a **MetaBox** which may be present in the movie header or in movie fragment headers.

Items carrying glTF may serve either as an entry point to the file (e.g. as determined by the application using the ISOBMFF file or when the ISOBMFF is loaded with a URL with fragment identifier identifying that item) or as secondary content loaded by either other items or track samples.

### glTF Items

The brand '**glti**' may be used to signal the use of a **MetaBox** with the following constraints:

It shall be present at the file level.

It shall use a **HandlerBox** with the handler\_type set to '**gltf**'

It shall contain a **PrimaryItemBox** which declares as primary item a resource of type 'model/gltf+json'.

It shall not use any **DataInformationBox**, **ItemProtectionBox** or **IPMPControlBox**.

It shall use a **ItemInfoBox** '**iinf**' with the following constraints:

its version is either 0 or 1;

each item is described by an **ItemInfoEntry** '**infe**' with the following constraints:

its version is set to 0;

its **item\_protection\_index** is set to 0;

if the item is referred to by a URL in the content of another item, its **item\_name** is equal to that URL.

It shall use an **ItemLocationBox** '**iloc**' with the following constraints:

its version is set to 1 or 2;

each item is described by an entry and values 0, 1 or 2 may be used for the construction method.

It may use any other boxes (such as **ItemReferenceBox** '**iref**') not explicitly excluded above.

It may contain a **GroupsListBox** with a **EntityToGroupBox** with the grouping type '**gltf**', containing an array of **entity\_id** which is resolved to this item and to all the tracks in this file referenced by the glTF object stored in this item.

NOTE This entity grouping helps file parsers to understand the relationships between the item and the tracks present in the file without having to parse the glTF file in the item.

### glTF source items

A glTF Source Object is a scene description source document and can be carried as s glTF Source Item. The brand '**glsi**' may be used to signal the use of a **MetaBox** with the following constraints:

It shall be present at the track level, the containing track shall comply to [subclause 7.2](#Section_sec_7.2).

It shall use a **HandlerBox** with the handler\_type set to '**glsi**'

It shall contain a **PrimaryItemBox** which declares as primary item a resource of type '**application/json**'.

It shall not use any **DataInformationBox**, **ItemProtectionBox** or **IPMPControlBox**.

It shall use a **ItemInfoBox** '**iinf**' with the following constraints:

its version is either 0 or 1;

each item is described by an **ItemInfoEntry** '**infe**' with the following constraints:

its version is set to 0;

its **item\_protection\_index** is set to 0;

if the item is referred to by a URL in the content of another item, its **item\_name** is equal to that URL.

It shall use an **ItemLocationBox** '**iloc**’ with the following constraints:

its version is set to 1 or 2;

each item is described by an entry and values 0, 1 or 2 may be used for the construction method.

It may use any other boxes (such as **ItemReferenceBox** '**iref**') not explicitly excluded above.

It may contain a **GroupsListBox** with a **EntityToGroupBox** with the grouping type '**gltf**', containing an array of **entity\_id** which is resolved to this item and to all the tracks in this file referenced by the glTF object stored in this item.

## Carriage format for mesh correspondence values

### General

A sample in a metadata track is used to provide the correspondence values that are used to map one mesh, i.e. dependent mesh, to another mesh, i.e. shadow mesh. The sample timing of the metadata track defines the time instant of a mesh sample to which the correspondence value applies. The sample format itself contains an integer value that identifies the indexed face of the shadow mesh to which the corresponding vertex applies.

In glTF JSON file, the correspondence values are provided through an extension of a mesh by referring to an accessor with MPEG\_accessor\_timed extension. The number of correspondence values within a sample and the number of vertices of the corresponding mesh shall be the same.

### Vertices correspondence sample entry

#### Definition

|  |  |
| --- | --- |
| Sample Entry Type: | 'vcor' |
| Container: | Sample Description Box ('stsd') |
| Mandatory: | No |
| Quantity: | 0 or 1 |

A vertex correspondence entry identifies a track containing vertex correspondence samples.

#### Syntax

aligned(8) class VertexCorrespondenceSampleEntry()  
   extends MetadataSampleEntry('vcor') {  
   unsigned int(3) precision;  
   bits(5) reserved;  
}

#### Semantics

* **precision** specifies the length in bytes of the correspondence values within each sample. The value of precision shall be greater than 0 and smaller or equal to 4.

### Vertices correspondence sample format

#### General

The sample format includes the number of correspondence values, as well as the value itself that applies to each of the vertices.

#### Syntax

aligned(8) class VerticesCorrespondenceSample  
{   unsigned int(32) vertex\_count;  
    for( i = 0; i < vertex\_count; i++ ){  
    unsigned int(8 \* precision) face\_index[ i ];  
    }  
}

#### Semantics

* **vertex\_count** specifies the number of vertices of the mesh this sample applies to and the number of **face\_index**[ i ] values present in the sample
* **face\_index**[ i ] specifies the index of a face in a shadow mesh to which a vertex with index equal i of dependent mesh is mapped.

#### Processing of correspondence samples

The value of precision in VertexCorrespondenceSampleEntry is constraint as follows. When precision is equal to 1, the componentType of the accessor referenced by correspondence attribute in the corresponding mesh with the MPEG\_mesh\_linking extension shall be equal to UNSIGNED\_BYTE (5121). Otherwise, when precision is equal to 2, the componentType of the accessor referenced by correspondence attribute in the corresponding mesh with the MPEG\_mesh\_linking extension shall be equal to UNSIGNED\_SHORT (5123). Otherwise, when precision is equal to 3 or 4, the componentType of the accessor referenced by correspondence attribute in the corresponding mesh with the MPEG\_mesh\_linking extension shall be equal to UNSIGNED\_INT (5125).

The samples VerticesCorrespondenceSample are processed as follows. **vertex\_count** shall be made available as "count" in the corresponding timed accessor information header fields in the corresponding frame of the circular buffer, which the accessor with the MPEG\_accessor\_timed indicated by correspondence attribute in the MPEG\_mesh\_linking extension points to. **face\_index**[ i ] shall be made available in the corresponding frame of the circular buffer, which the accessor with the MPEG\_accessor\_timed indicated by correspondence attribute in the MPEG\_mesh\_linking extension points to using the componenType specified above.

## Carriage format for pose and weight

### General

A sample in a metadata track is used to provide the pose transformation used onto the shadow mesh and weight values that are used to apply the morph targets of the shadow mesh to transform the shadow mesh to the corresponding position and pose of the dependent mesh. The sample timing of the metadata track defines the time instant of a mesh sample to which the pose and weight information applies. The sample format itself contains the transformations matrix to be applied onto the nodes of the skeleton of the mesh and "weight" values to apply the morph targets of the shadow mesh.

In glTF JSON file, the specified values are provided through an extension of a mesh by referring to an accessor with MPEG\_accessor\_timed extension. The number of "weight" values within a sample and the number of morph target of the corresponding shadow mesh shall be the same.

### Pose transformation sample entry

#### Definition

|  |  |
| --- | --- |
| Sample Entry Type: | 'post' |
| Container: | Sample Description Box ('stsd') |
| Mandatory: | No |
| Quantity: | 0 or 1 |

A pose transformation sample entry identifies a track containing pose transformation samples.

#### Syntax

aligned(8) class PoseTransformationSampleEntry( )  
extends MetadataSampleEntry( 'post' ) {  
   unsigned int(16) number\_of\_nodes;  
   for( unsigned int i = 0; i < number\_of\_nodes; i++ ){  
      unsigned int (32) node\_index[ i ];  
   }  
   unsigned int(16) number\_of\_morph\_targets;  
}

#### Semantics

* **number\_of\_nodes** specifies the number of nodes for which the transformation is described.
* **node\_index**[ i ] specifies the index of the nodes array in the glTF file which the i-th node in the sample applies to.
* **number\_of\_morph\_targets** specifies the number of morph targets for which a weight is provided.

### Pose transformation sample format

#### General

The sample format includes the transformations for each node, as well as weights to be applied to the associated morph targets.

#### Syntax

aligned(8) class PoseTransformationSample {  
   for( i = 0; i < number\_of\_nodes; i++ ){  
      float(32) [16] matrix[ i ];  
   }  
   for( i = 0; i < number\_of\_morph\_targets; i++ ){  
      float(32) weight[ i ];  
   }  
}

#### Semantics

* **matrix**[ i ] specifies the transformation matrix of the i-th node.
* **weight**[ i ] specifies the weight to be applied to the i-th morph target.

#### Processing of pose transformation samples

The **PoseTransformationSampleEntry** is processed as follows. When immutable is set to True and bufferView is not present the accessor within the MPEG\_accessor\_timed extension indicated by pose attribute or weights attribute in the MPEG\_mesh\_linking extension, the value of count in the corresponding accessor shall be equal to number\_of\_nodes or number\_of\_morph\_targets, respectively. Otherwise, the syntax element number\_of\_nodes shall be made available as count attribute in the corresponding timed accessor information header fields in the corresponding frame of the circular buffer, which the accessor with the MPEG\_accessor\_timed indicated by pose attribute in the MPEG\_mesh\_linking extension points to, and syntax element number\_of\_morph\_targets shall be made available as count attribute in the corresponding timed accessor information header fields in the corresponding frame of the circular buffer, which the accessor with the MPEG\_accessor\_timed indicated by weights attribute in the MPEG\_mesh\_linking extension points to.

The samples in **PoseTransformationSample** are processed as follows. matrix[ i ] shall be made available in the corresponding frame of the circular buffer, which the accessor with the MPEG\_accessor\_timed indicated by pose attribute in the MPEG\_mesh\_linking extension points to. Similarly, weight[ i ] shall be made available in the corresponding frame of the circular buffer, which the accessor with the MPEG\_accessor\_timed indicated by weight attribute in the MPEG\_mesh\_linking extension points to.

## Carriage format for animation timing

### General

A sample in a metadata track is used to manipulate an animation event defined in the glTF JSON file. The sample timing of the metadata track defines, when in the global timeline (i.e. common for audio/video/animation) the animation should be manipulated. The metadata track may be stored in the ISOBMFF file along with other media, which provides utility to align manipulations of glTF animations with the video and audio tracks.

The default duration of the animation would be defined by the animation data in the binary glTF buffer and not by the sample duration of ISOBMFF.

### Animation sample entry

#### Definition

|  |  |
| --- | --- |
| Sample Entry Type: | 'glat' |
| Container: | Sample Description Box ('stsd') |
| Mandatory: | No |
| Quantity: | 0 or 1 |

An animation sample entry identifies an animation track containing glTF animation samples.

#### Syntax

aligned(8) class glTFAnimationSampleEntry()  
   extends MetadataSampleEntry('glat') {  
}

### Animation sample format

#### General

The sample format includes controlling parameters for animations defined in the glTF animations array.

#### Syntax

aligned(8) class glTFAnimationSample  
{  
   unsigned int(1) apply\_to\_all;  
   unsigned int(7) reserved;  
   unsigned int(16) num\_events;  
   for( i=0; i < num\_events; i++ ){  
      unsigned int(32) index[i];  
      int(32) speed[i];  
      unsigned int(8) state[i];  
      if( state == 6 ){  
         unsigned int (32) start\_frame[i];  
         unsigned int (32) end\_frame[i];  
      }  
      unsigned int (8) order\_id[i];  
      unsigned int(32) num\_channels[i];  
      for( int j = 0; j < num\_channels[i]; j++) {  
         int (8) weight[i][j];  
         unsigned int (32) channel\_index[i][j];  
      }  
   }  
}

#### Semantics

* **apply\_to\_all** if equal to 1, the num\_events shall equal 1 and the animation event in the sample is applied to all animations in the glTF animations array.
* **num\_events** – specifying number of animation events triggered at the time of the sample.
* **index[ i ]** specifies the index value of animation in animation node described in the glTF json file.
* **speed[ i ]**specifies a multiplier which indicate the speed of the playout of the animation. A negative value may indicate that the animation should be played in a reverse order, from the end to the start. The speed is stored as signed 15.16 fixed-point value.
* **state[ i ]** specifies status of the animation as defined in [Table 25](#Table_tab_25).
* **start\_frame[ i ]** specifies the key frame of the animation used after each loop.
* **end\_frame[ i ]** specifies the last the key frame of the animation before looping the animation.
* **order\_id[ i ]** specifies a value to indicate the order in which animations are applied. Animations with lower values are applied before animation with higher values.
* **num\_channels[ i ]**specifies the number of channels of an animation for which a weight is provided.
* **weight[ i ][ j ]** specifies the weight to be applied to the j-th channel of the animation in units of 1/255.
* **channel\_index[ i ][ j ]** specifies the index of the j-th channel of the animation.

Table 25 — Definition of the state values in animation sample format

| **state value** | **identifier** | **description** |
| --- | --- | --- |
| 0 | play | Play the animation |
| 1 | stop\_at\_initial | Stop the animation and return to the initial state |
| 2 | stop\_at\_final | Stop the animation and keep the final state |
| 3 | pause | Pause animation |
| 4 | restart | Restart the animation, equivalent to stopping animation and playing it from the beginning. |
| 5 | update | Update the animation characteristic, e.g. speed |
| 6 | loop | Sets the animation to be applied repeatedly in a loop. |
| 7 | loop\_relative | Set the animation to be applied repeatedly in a loop with initial object position of the current loop being the final object position of the previous loop |
| 8..63 | reserved | Reserved for future use |

## Sample redundancies

For all tracks defined in this document, if a sample has its **sample\_has\_redundancy** flag set, it is expected that that sample would only be made available by the ISOBMFF parser to the Presentation Engine if the processing of the file starts with this sample. Otherwise, it is expected that the sample be ignored, and that processing of the current sample is continued for a duration equal to the duration of the ignored sample, as defined in ISO/IEC 14496-12.

## Brands

The brand **'gltf'** may be present among the **compatible\_brands of the FileTypeBox**.

The brand **'gltf'** shall be used to indicate that the file is conformant with the file format specified in [subclauses 7.2](#Section_sec_7.2).

The brand **'glti'** may be present among the **compatible\_brands of the FileTypeBox**.

The brand **'glti'** shall be used to indicate that the file is conformant with the file format specified in [subclauses 7.3](#Section_sec_7.3).

(informative)  
  
JSON schema reference

General

JSON schemas glTFChildOfRootProperty.schema.json, glTFProperty.schema.json, and glTFid.schema.json references in [subclauses 5.2](#Section_sec_5.2), [5.3](#Section_sec_5.3), [5.4](#Section_sec_5.4), and [5.5](#Section_sec_5.5) are defined in ISO/IEC 12113.

JSON schema for MPEG\_media

MPEG\_media.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_media.schema.json>.

MPEG\_media.media.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_media.media.schema.json>.

MPEG\_media.media.alternative.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_media.media.alternative.schema.json>.

MPEG\_media.media.alternative.track.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_media.media.alternative.track.schema.json>.

JSON schema for MPEG\_accessor\_timed

MPEG\_accessor\_timed.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_accessor_timed.schema.json>.

JSON schema for MPEG\_buffer\_circular

MPEG\_buffer\_circular.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_buffer_circular.schema.json>.

JSON schema for MPEG\_scene\_dynamic

MPEG\_scene\_dynamic.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_scene_dynamic.schema.json>.

JSON schema for MPEG\_texture\_video

MPEG\_texture\_video.schema.json schema is downloadable from   
<https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_texture_video.schema.json>.

JSON schema for MPEG\_mesh\_linking

MPEG\_mesh\_linking.schema.json schema is downloadable from   
<https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_mesh_linking.schema.json>.

JSON schema for MPEG\_audio\_spatial

MPEG\_audio\_spatial.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_audio_spatial.schema.json>.

MPEG\_audio\_spatial.source.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_audio_spatial.source.schema.json>.

MPEG\_audio\_spatial.reverb.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_audio_spatial.reverb.schema.json>.

MPEG\_audio\_spatial.reverb.property.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_audio_spatial.reverb.property.schema.json>.

MPEG\_audio\_spatial.listener.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_audio_spatial.listener.schema.json>.

JSON schema for MPEG\_viewport\_recommended

MPEG\_viewport\_recommended.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_viewport_recommended.schema.json>.

MPEG\_viewport\_recommended.viewport.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_viewport_recommended.viewport.schema.json>.

JSON schema for MPEG\_animation\_timing

MPEG\_animation\_timing.schema.json schema is downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/MPEG_animation_timing.schema.json>.

(normative)  
  
Attribute registry

[Table B.1](#Table_tab_B.1) provides a registry of the MPEG-defined attributes and their semantics. Attributes defined by MPEG shall use the \_MPEG prefix and namespace and shall be registered in this table. A registry shall provide at least a name, the accessor type, component type, and a description. It is recommended that they also provide an example shader program in the OpenGL® Shading Language (GLSL).

Table B.1 — MPEG attribute registry

| **Name** | **Accessor type(s)** | **Component type(s)** | **Description** | **Reference and example shader program** |
| --- | --- | --- | --- | --- |
| \_MPEG\_V3C\_ATTR\_REFLECTANCE | scalar | 5123 | indicates the reflectance information that is associated with each point in a volumetric frame. |  |
| \_MPEG\_V3C\_ATTR\_MATERIAL\_ID | scalar | 5123 | indicates a supplemental information that identifies material type of a point in a volumetric frame. |  |
| \_MPEG\_V3C\_ATTR\_TRANSPARENCY | scalar | 5123 | indicates the transparency information that is associated with each point in a volumetric frame. |  |

(normative)  
  
Support for real-time media

This Annex defines a URL scheme that shall be used when referencing in the MPEG\_media extension external media streams that are delivered over RTP/SRTP:

   url = scheme ":" hier-part "?" query  
   scheme = "rtp" / "srtp" / "rtmedia"  
   hier-part = "//" host [":" port]  
   host = IP-literal / reg-name / "@"  
   query = stream-identifier \*("&" parameter)  
   stream-identifier = mid / label / index  
   mid = "mid=" identification-tag  
   label = "label=" pointer  
   index = "index=" num-val  
   parameter = key "=" value  
   key = char-val  
   value = char-val / num-val

This scheme allows for addressing media streams without actually knowing the values for the protocol scheme, hostname, or port. It requires the presence of a stream-identifer in the query part. However, it doesn’t dictate a specific type of identifier. It allows for the usage of the Media Stream Identification scheme (RFC 5888), a labeling scheme (RFC 4575), or a 0-based indexing scheme. The SDP of the session that carries the referenced media stream shall have the corresponding stream identifier, in case mid or label reference is used, or it shall contain the media stream in the correct position, in case an index reference is used.

The ABNF format for URI as defined in RFC3986 defines the syntax for IP-literal and reg-name. The ABNF syntax as well as the definition for char-val and num-val are defined in RFC 5234. RFC 5888 defines the syntax for identification-tag. RFC 4574 defines the syntax for pointer.

The following is an example of a URL that references a real-time media stream for which neither the host and port, nor the protocol scheme is yet known.

   rtmedia://@?label=depth1

The following example is for a reference to a media stream, where the protocol scheme, destination IP address, port number, and the mid are known.

   srtp://192.168.100.100:9000?mid=2

The corresponding SDP description may be as follows:

   m=video 9000 UDP/TLS/RTP/SAVPF 96  
   c=IN IP4 192.168.100.100  
   a=rtpmap:96 H265/90000  
   a=fmtp:96 profile-id=1; level-id=153; sprop-  
   vps=QAEMAf//AWAAAAMAgAAAAwAAAwBdLAUg; sprop-  
   sps=QgEBAWAAAAMAgAAAAwAAAwBdoAKAgC0WUuS0i9AHcIBB; sprop-  
   pps=RAHAcYDZIA==  
   a=rtcp:9 IN IP4 0.0.0.0  
   a=mid:2  
   a=recvonly  
   a=rtcp-mux

(normative)  
  
Audio attenuation functions

General

This Annex defines a set of audio source attenuation functions and their parameters. The attenuation functions defined in this document are defined according to the corresponding clamped attenuation models as defined by Reference [[5](#Reference_ref_11)]. If the attenuation function cannot be evaluated for a distance, then the audio signal shall not be attenuated.

For all the attenuation functions defined in this document, distance represents the distance between the audio source and the audio listener and the reference distance is provided through referenceDistance property as defined in [Table 14](#Table_tab_14). The attenuation function is used to determine the distance gain.

No attenuation (no\_attenuation)

This attenuation function results in a distance gain of 1.0, thus corresponding to no attenuation.

Inverse distance attenuation (inverse\_distance)

The inverse distance attenuation function *ida(d, md, rf)* is defined as follows:

Where *md* is maximum distance, *rf* is roll factor, *rd* is reference distance, and *d* is the distance for which the distance gain is calculated.

Linear distance attenuation (linear\_distance)

The linear distance attenuation function *lda(d, md*, *rf*) is defined as follows:

Where *md* is maximum distance, *rf* is roll factor, *rd* is reference distance, and *d* is the distance for which the distance gain is calculated.

Exponential distance attenuation (exponential\_distance)

The exponential distance attenuation function *eda(d, md, rf)* is defined as follows:

Where *md* is maximum distance, *rf* is roll factor, *rd* is reference distance, and *d* is the distance for which the distance gain is calculated.

Custom attenuation

The custom attenuation function is identified through a mandatory input parameter “identifier” and a set of custom parameters.

(informative)  
  
Linking a dependent mesh and its associated shadow mesh

Each vertex of the dependent mesh at time *t* is represented by *vd,i*(*t*) with *i*=0..*Nd*(*t*) – 1 with *Nd*(*t*) being the number of vertices of the dependent mesh at time *t*.

Each vertex of the shadow mesh is represented by *vs,i* with *i*=0.. *Ns* – 1 with *Ns* being the number of vertices of the shadow mesh. Note that the shadow mesh is static and therefore it does not depend on the time.

*Wj*(*t*) represents the weight for the *j*-th morph targets (*mj*) that needs to be applied at time *t*.

The mesh primitive of the shadow mesh contains attributes that are required for the vertex skinning. Particularly, these are the “JOINTS\_0” and the “WEIGHTS\_0” attributes, with “JOINTS\_0” indicating for each vertex which of the *K* joints has an influence on a vertex during the skinning process and the “WEIGHTS\_0” attribute indicating how strongly each joint influences each vertex. With these attributes, weights *αk,i* for the transformation *Tk* of a vertex *i* due to joint *k* can be determined.

The skinning operation is applied on the vertices of the shadow mesh after applying the offset determined by the morph targets as in ([E.1](#_p_formula_E.1)).

(E.1)

At this point the shadow mesh is at the same position and pose as the dependent mesh. Using the correspondence information, each vertex of the dependent mesh *vd,i*(*t*) at time *t* is mapped to the *ci*(*t*)-th face, where *ci*(*t*) is the correspondence value indicated for the *i*-th vertex of the dependent mesh at time *t*. The three vertices corresponding to each face of the shadow mesh at the same position as the dependent mesh and indicated by a correspondence value *ci*(*t*)-th are represented by *v’s,j*(*t*), *v’s,k*(*t*) and *v’s,l*(*t*).

The distance from *vd,i*(*t*) to the plane defined by *v’s,j*(*t*), *v’s,k*(*t*) and *v’s,l*(*t*) and the projected point within the given face *pi*(*t*) is computed as follows.

The orthonormal vector to the *ci*(*t*)-th face is defined as:

(E.2)

whereis representing the cross product of two vectors.

The vector (*v’s,j*(*t*) – *vd,i*(*t*)) is projected ontoand added to the vertex *vd,i*(*t*) to determine the point *pi*(*t*).

(E.3)

And the distance to the plane is determined as:

(E.4)

The sign *si* of the product of the orthonormal vectorand the vector normalized is computed:

(E.5)

Finally, the projected point *pi*(*t*) is transformed to barycentric coordinates as follows:

(E.6)

(E.7)

(E.8)

whereis representing the cross product of two vectors.

(E.9)

Thus, when the *ci*(*t*)-th face of the shadow mesh is transformed by an animation, the computed barycentric coordinate can be used at that face represented by *v’’s,j*(*t*), *v’’s,k*(*t*) and *v’’s,l*(*t*) and using the corresponding point and the computed distance the corresponding vertex of the dependent mesh *v’d,i*(*t*) can be determined at the same relative position as follows.

(E.10)

(E.11)

(E.12)

(informative)  
  
glTF extension usage examples

MPEG\_media

In the example downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example_MPEG_media.json>, two media items are listed by MPEG\_media extension. The first media item contains only one item within alternatives, which is a DASH manifest that contains one track. Even though there are no alternatives at the media level, DASH manifest may still have different Representations within the Adaptation Set (but this is outside of the scope of the extension). The second media item contains two items within the alternatives. The first one lists an ISOBMFF file that contains data compressed using AVC codec, while the second one lists an mp4 file that contains data compress using HEVC codec. However, each track item may contain different information, which depends on the structure of the ISOBMFF file.

MPEG\_accessor\_timed

In the example downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example_MPEG_accessor_timed.json> a usage of MPEG\_accessor\_timed is presented.

MPEG\_buffer\_circular

In the example downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example_MPEG_buffer_circular.json> a usage of MPEG\_buffer\_circular is presented.

MPEG\_scene\_dynamic

In the example downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example_MPEG_scene_dynamic.json>, the media object includes the patch document format file name and its track index. The mimeType indicates that the data is patch information for dynamic scene updates.

MPEG\_texture\_video

In the example downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example_MPEG_texture_video.json>, two texture items are listed. Each texture item use MPEG\_texture\_video extension. The first texture item is expected to be available in buffer indicated by accessor 2. The second texture item is expected to be available in buffer indicated by accessor 3.

MPEG\_mesh\_linking

In the example downloadable from <https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example_MPEG_mesh_linking.json>, two mesh items are listed. The second mesh item uses MPEG\_mesh\_linking extension. Mesh at mesh.index: 0, is the shadow mesh. The primitive information such as JOINTS, WEIGHTS for the mesh of the shadow mesh is available. The mesh entity at index:0 also includes morph targets which are applied in order to correct artefacts introduced during the skinning operation. The mesh entity at mesh.index: 1, is the dependent mesh ( e.g., volumetric scan object). The extension “MPEG\_mesh\_linking” includes the mapping information in “correspondence” which can be determined using the accessor index. The extension includes the mesh.index value indicating the shadow mesh to which the dependent mesh including the extension is linked and to which the mapping information corresponds to. The extension also includes “pose” and “weights” attributes which indicate the accessors with the transformations of the pose of the dependent mesh at a particular time and the weights to be used for each of the morph targets of the shadow mesh for that particular pose.

MPEG\_audio\_spatial

In the example downloadable from [https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example\_MPEG\_audio\_spatial.json](https://standards.iso.org/iso-iec/23090/-14/ed-1/en/Schema/example_MPEG_audio_spatial.json), a usage of MPEG\_audio\_spatial is presented.

MPEG\_viewport\_recommended

In the example downloadable from [https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example\_MPEG\_viewport\_recommended\_01.json](https://standards.iso.org/iso-iec/23090/-14/ed-1/en/Schema/example_MPEG_audio_spatial.json), one camera object is listed. This camera object uses MPEG\_viewport\_recommended extension. It is expected that recommended viewport information will be available in the buffer indicated by timed accessors 0, 1, and 2.

In the example downloadable from [https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example\_MPEG\_viewport\_recommended\_02.json](https://standards.iso.org/iso-iec/23090/-14/ed-1/en/Schema/%20example_MPEG_viewport_recommended_02.json), one media object is listed. This media object includes the recommended viewport file name and its track index. The mimeType indicates that the data is recommended viewport information.

MPEG\_animation\_timing

In the example downloadable from [https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example\_MPEG\_animation\_timing.json](https://standards.iso.org/iso-iec/23090/-14/ed-1/en/Schema/%20example_MPEG_viewport_recommended_02.json), a usage of MPEG\_animation\_timing is presented.

Full example

In the example downloadable from [https://standards.iso.org/iso-iec/23090/-14/ed-1/en/example\_full\_01.json](https://standards.iso.org/iso-iec/23090/-14/ed-1/en/Schema/example_full_01.json), a usage of MPEG\_media, MPEG\_buffer\_cricular, MPEG\_accessor\_timed, MPEG\_audio\_spatial, and MPEG\_animation\_timing extensions is presented.

MPEG\_primitive\_V3C

In the example downloadable from https://standards.iso.org/iso-iec/23090/-14/ed-1/en/amd/1/example\_MPEG\_primitive\_V3C, a usage of the MPEG\_primitive\_V3C is presented.

MPEG\_sampler\_YCbCr

In the example downloadable from https://standards.iso.org/iso-iec/23090/-14/ed-1/en/amd/1/example\_MPEG\_sampler\_YCbCr, a usage of the MPEG\_sampler\_YCbCr extension is presented.

Support for MPEG-I Media

## MPEG\_primitive\_V3C extension

### General

In order to support V3C compressed objects in MPEG-I scene description, the MPEG\_media extension is used to refer to V3C compressed bitstreams.

The presentation engine may support the operations to perform the 3D reconstruction of decoded V3C components as indicated in the Figure 2. The presentation engine accesses the decoded V3C data through buffers.

The syntax of the V3C object is provided as an extension to mesh.primitive in a scene description format. The extension refers to the decoded data of a V3C object. Each decoded V3C component is signalled using properties defined in the MPEG\_primitive\_V3C extension. The extension is specific to objects coded with a V3C compression scheme (i.e., ISO/IEC 23090-5 [2] or ISO/IEC 23090-12 [3]).

Usage of the extension must be listed in the *extensionsUsed* top-level glTF property.

"*extensionsUsed*": [

"MPEG\_primitive\_V3C"

]

Figure G.1 depicts the structure of the V3C mesh compression extension:

A screenshot of a computer

Description automatically generated

Figure G.1 Example structure of V3C compressed primitive

If the Presentation Engine does not support the MPEG\_primtive\_V3C extension, It shall request the reconstructed raw data as described by the primitive attributes.

### Semantics

An MPEG\_primitive\_V3C extension refers to several V3C components, containing the decoded projected maps and metadata necessary such as atlas data for the 3D reconstruction process.

Table G.1 provides a list of the possible components and their description:

Table G.1 MPEG\_primitive\_V3C properties

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Name** | **Type** | **Default** | **Usage** | **Description** |
| \_MPEG\_V3C\_CONFIG | Integer | N/A | M | This component provides a reference to a timed accessor that contains configuration information that is applicable to a sequence of frames of the V3C decoded mesh primitive. The binary format of the configuration buffer is provided in clause G.1.3. |
| \_MPEG\_V3C\_AD | Object | N/A | M | this component shall reference a timed accessor that provides the V3C atlas data buffer. The atlas buffer format is defined in clause G.1.4. Future specifications of the atlas data buffer format shall use a different version.  Exactly one atlas component shall be present, irrespective of the version. |
| \_MPEG\_V3C\_GVD\_MAPS | array(integer) | N/A | M | this component shall provide an array of video texture references, each of which corresponds to one map of the decoded geometry video data. |
| \_MPEG\_V3C\_OVD\_MAP | integer | N/A | O | this component shall provide a video texture reference, which corresponds to the decoded occupancy video data map. |
| \_MPEG\_V3C\_AVD | array(object) | N/A | O | this component shall provide an array of objects, each of which describing an attribute component of the V3C compressed mesh primitive. The properties of the components are described in Table G.2. |
| \_MPEG\_V3C\_CAD | Object | N/A | CM | This object lists different properties described for the Common Atlas Data in ISO/IEC 23090-5. |
| Legend:  For attributes: M=mandatory, O=optional, OD=optional with default value, CM=conditionally mandatory. | | | | |

The \_MPEG\_V3C\_AD object shall have the structure as describe in Table G.2:

Table G.2 Properties of \_MPEG\_V3C\_AD object

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Name** | **Type** | **Default** | **Usage** | **Description** |
| buffer\_format | String | "baseline” | O | provides an identifier of the associated atlas data buffer format. A list of supported atlas data buffer formats is provided in Table G.4. |
| accessor | Integer | N/A | M | This provides the index of the timed accessor that provides access to the atlas data buffer. |

The \_MPEG\_V3C\_AVD object shall have the following structure:

Table G.3 Properties of \_MPEG\_V3C\_AVD object

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Name** | **Type** | **Default** | **Usage** | **Description** |
| type | uint8 | 0 | O | provides the type of the attribute as defined by the “V3C attribute types” in ISO/IEC 23090-5. |
| maps | array(integer) | N/A | M | This array shall provide a list of video texture references, each of which corresponds to one map of the decoded attribute video data. |

Each mesh primitive shall reference exactly one atlas data buffer.

Different buffer formats with unique string identifier for the atlas data are defined in Table G.4.

Table G.4 List of atlas data buffer formats

|  |  |
| --- | --- |
| **buffer\_format** | **Description** |
| baseline | The configuration data is defined in Table G.5 and the corresponding atlas data buffer format is defined in Table G.6. |
| extended | Atlas data with common atlas parameters and and PROJECTED patch type application-specific data with PLR information, EOM patch type application-specific data, and RAW patch type application-specific data. The configuration data format is defined in G.5 and the corresponding atlas data buffer format is defined in Table G.7. |
| miv | Atlas data with common atlas parameters and PROJECTED patch type application-specific parameters for MIV. The configuration data format is defined in G.5 and the corresponding atlas data buffer format is defined in Table G.8. |

### Configuration Data Buffer Format

The configuration data buffer is binary formatted data that provides static configuration data that is applicable for the V3C compressed primitive. The data shall comply to the following format:

Table G.5 Configuration data buffer format

|  |  |  |
| --- | --- | --- |
| **Field** | **Type** | **Description** |
| **frame\_width** | uint16 | indicates the frame width in luma samples of the atlas and all other associated V3C components. |
| **frame\_height** | uint16 | indicates the frame height in luma samples of the atlas and all other associated V3C components. |
| **map\_count** | uint8 | indicates the number of maps used for encoding the geometry and attribute data for the current atlas. |
| **patch\_packing\_block\_size** | uint8 | specifies the value of the variable PatchPackingBlockSize in ISO/IEC 23090-5, that is used for the horizontal and vertical placement of the patches within the current atlas. |

### Atlas Data Buffer Format

The atlas data buffer is binary formatted data that shall comply to the following formats in Table G.6, Table G.7 and Table G.8 depending on the buffer format for the atlas data. The atlas buffer format for “buffer\_format” value “baseline” is described in Table G.7.

Table G.6 Atlas data buffer format for buffer\_format:baseline

|  |  |  |
| --- | --- | --- |
| **Field** | **Type** | **Description** |
| **patch\_count** | uint16 | provides the total number of patches. |
| for( i=0;i<patch\_count;i++ ) { |  |  |
| **2d\_pos\_x** | Float | specifies the x-coordinate of the top-left corner of the patch bounding box for the current patch. |
| **2d\_pos\_y** | Float | specifies the y-coordinate of the top-left corner of the patch bounding box for the current patch. |
| **2d\_size\_x** | Float | specifies the width of the current patch. |
| **2d\_size\_y** | Float | specifies the height of the current patch. |
| **3d\_offset\_u** | Float | specifies the shift to be applied to the reconstructed patch points in the current patch along the tangent axis. |
| **3d\_offset\_v** | Float | specifies the shift to be applied to the reconstructed patch points in the current patch along the bi-tangent axis. |
| **3d\_offset\_d** | Float | specifies the shift to be applied to the reconstructed patch points in the current patch along the normal axis. |
| **patch\_projection\_id** | uint8 | specifies the identifier of the projection mode and the index of the normal to the projection plane of the current patch. |
| **patch\_orientation** | uint8 | specifies the index of the patch orientation of the current patch. |
| **lod\_scale\_x** | uint16 | specifies the LOD scaling factor to be applied to the tangent axis of the current patch. |
| **lod\_scale\_y** | uint16 | specifies the LOD scaling factor to be applied to the bi-tangent axis of the current patch. |
| } |  |  |

The atlas buffer format for “buffer\_format” value “extended” is described in Table G.7.

Table G.7 Atlas data buffer format for buffer\_format:extended

|  |  |  |
| --- | --- | --- |
| **Field** | **Type** | **Description** |
| patch\_count | uint16 | provides the total number of patches. |
| for ( i=0;i<patch\_count;i++ ) { |  |  |
| patch\_type | uint8 | specifies the type of patch |
| 2d\_pos\_x | float | specifies the x-coordinate of the top-left corner of the patch bounding box for the current patch. |
| 2d\_pos\_y | float | specifies the y-coordinate of the top-left corner of the patch bounding box for the current patch. |
| 2d\_size\_x | float | specifies the width of the current patch. |
| 2d\_size\_y | float | specifies the height of the current patch. |
| 3d\_offset\_u | float | specifies the shift to be applied to the reconstructed patch points in the current patch along the tangent axis. |
| 3d\_offset\_v | float | specifies the shift to be applied to the reconstructed patch points in the current patch along the bi-tangent axis. |
| 3d\_offset\_d | float | specifies the shift to be applied to the reconstructed patch points in the current patch along the normal axis. |
| patch\_projection\_id | uint8 | specifies the identifier of the projection mode and the index of the normal to the projection plane of the current patch. |
| patch\_orientation | uint8 | specifies the index of the patch orientation of the current patch. |
| lod\_scale\_x | uint16 | specifies the LOD scaling factor to be applied to the tangent axis of the current patch. |
| lod\_scale\_y | uint16 | specifies the LOD scaling factor to be applied to the bi-tangent axis of the current patch. |
| if (patch\_type == PROJECTED) { |  |  |
| plri\_map\_present | bool | specifies if the plr information is present |
| if (plri\_map\_present) { |  |  |
| plrd\_level | bool | specifies the level of PLR data for a patch |
| if (plr\_level == 0 ) { |  |  |
| for ( b = 0; b < blockcount < b++) { |  |  |
| plrd\_present\_block\_flag | bool | specifies whether the PLR data is present for a block |
| if (plrd\_present\_block\_flag == 1) { |  |  |
| plrd\_block\_mode | uint8 | specifies the mode of PLR data for a block |
| } |  |  |
| } |  |  |
| } else { |  |  |
| plrd\_present\_patch\_flag | bool | specifies whether the PLR data is present for the patch |
| if (plrd\_present\_patch\_flag) { |  |  |
| plrd\_patch\_mode | uint8 | specifies the mode of the PLR data for the patch |
| } |  |  |
| } |  |  |
| } |  |  |
| else if (patch\_type == EOM) |  |  |
| eom\_patch\_count | uint8 | specifies the number of patches that may be associated with the current patch |
| eom\_points | uint8 | specifies the number of EOM coded points in the patch associated with the current patch |
| associated\_patch\_index | uint8 | specifies the index of the i-th patch associated with the current patch |
| } |  |  |
| else if (patch\_type == RAW) |  |  |
| raw\_points | uint8 | specifies the number of RAW coded points in the current patch |
| } |  |  |
| } |  |  |

Note: The calculation of blockCount is specified in function BlockCnt (xSize, ySize) in clause 8.4.7.9 of ISO/IEC 23090-5. The arguments to the function are patch dimensions, i.e., 2d\_size\_x, and 2d\_size\_y.

The atlas buffer format for “buffer\_format” value “miv” is described in Table G.8.

Table G.8 Atlas data buffer format for buffer\_format:miv

|  |  |  |
| --- | --- | --- |
| **Field** | **Type** | **Description** |
| patch\_count | uint16 | provides the total number of patches. |
| for( i=0;i<patch\_count;i++ ) { |  |  |
| 2d\_pos\_x | float | specifies the x-coordinate of the top-left corner of the patch bounding box for the current patch. |
| 2d\_pos\_y | float | specifies the y-coordinate of the top-left corner of the patch bounding box for the current patch. |
| 2d\_size\_x | float | specifies the width of the current patch. |
| 2d\_size\_y | float | specifies the height of the current patch. |
| 3d\_offset\_u | float | specifies the shift to be applied to the reconstructed patch points in the current patch along the tangent axis. |
| 3d\_offset\_v | float | specifies the shift to be applied to the reconstructed patch points in the current patch along the bi-tangent axis. |
| 3d\_offset\_d | float | specifies the shift to be applied to the reconstructed patch points in the current patch along the normal axis. |
| patch\_projection\_id | uint8 | specifies the identifier of the projection mode and the index of the normal to the projection plane of the current patch. |
| patch\_orientation | uint8 | specifies the index of the patch orientation of the current patch. |
| lod\_scale\_x | uint16 | specifies the LOD scaling factor to be applied to the tangent axis of the current patch. |
| lod\_scale\_y | uint16 | specifies the LOD scaling factor to be applied to the bi-tangent axis of the current patch. |
| patch\_view\_index | uint8 | specifies the index in the buffer format for the view parameter |
| patch\_entity\_id | uint8 | specifies the patch entity ID for the current patch |
| patch\_depth\_occ\_threshold | uint8 | specifies the threshold below with the occupancy value is defined to be unoccupied for the current patch |
| tile\_patch\_texture\_offset\_1 | uint8 | specifies the offset applied to the first component sample values of the attribute for the current patch |
| tile\_patch\_texture\_offset\_2 | uint8 | specifies the offset applied to the second component sample values of the attribute for the current patch |
| tile\_patch\_texture\_offset\_3 | uint8 | specifies the offset applied to the third component sample values of the attribute for the current patch |
| } |  |  |

### Common atlas data

#### G.1.5.1 Overview

The common atlas data is common to all atlases and shall correspond to the Common Atlas Data in ISO/IEC 23090-5.

#### G.1.5.2 MIV extension to CAD

Some of the common atlas data information which is common for the atlases in a V3C bitstream is specified in ISO/IEC 23090-12 such as view parameters. The syntax for the MIV extension to common atlas data is specified ISO/IEC 23090-12. It includes a list of view parameters which can be used during the rendering process (Annex H.1 in ISO/IEC 23090-12). An MIV\_view\_parameters property is defined for the \_MPEG\_V3C\_CAD object as shown in Table G.9.

The \_MPEG\_V3C\_CAD object can be extended to describe additional properties that may be introduced in future iterations of ISO/IEC 23090-5 or in extensions to that specification.

Table G.9 Definition of properties defined in \_MPEG\_V3C\_CAD in MPEG\_V3C extension

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Name** | **Type** | **Default** | **Usage** | **Description** |
| MIV\_view\_parameters | integer | N/A | O | This component provides a reference to a timed-accessor that contains the view parameters stored in the common atlas data that is applicable to a sequence of frames of the V3C decoded mesh primitive. The buffer format for the view parameters is described in Table G.10. |
| Legend:  For attributes: M=mandatory, O=optional, OD=optional with default value, CM=conditionally mandatory. | | | | |

#### G.1.5.3. Buffer format for MIV view parameters

Table G.10 describes the binary buffer format for view parameters.

Table G.10 Buffer format for view parameters

|  |  |  |
| --- | --- | --- |
| **Field** | **Type** | **Description** |
| num\_views | uint16 | number of views |
| for ( int p = 0; p < num\_views ; p++) { |  |  |
| view\_id\_to\_index | uint8 | mapping of the id associated with each view |
| view\_in\_paint\_flag | bool | specifies if the view is an inpaint view |
| view\_pos\_x | uint8 | specifies in scene units the x-coordinate of the location of the view with view index equal to v. |
| view\_pos\_y | uint8 | specifies in scene units the y-coordinate of the location of the view with view index equal to v. |
| view\_pos\_z | uint8 | specifies in scene units the z-coordinate of the location of the view with view index equal to v. |
| view\_quat\_x | uint8 | specifies the x components for the rotation of the view with view index equal to v using the quaternion representation |
| view\_quat\_y | uint8 | specifies the y components for the rotation of the view with view index equal to v using the quaternion representation |
| view\_quat\_z | uint8 | specifies the z components for the rotation of the view with view index equal to v using the quaternion representation |
| view\_quat\_w | uint8 | specifies the w components for the rotation of the view with view index equal to v using the quaternion representation |
| view\_type | uint8 | specifies the projection method of the view |
| projection\_plane\_width | uint8 | specifies the horizontal resolution of projection plane |
| projection\_plane\_height | uint8 | specifies the vertical resolution of the projection plane |
| if (view\_type == 0) { |  | equirectangular projection |
| erp\_phi\_min | float32 | specifies the minimum longitude range for an ERP projection in units of degrees |
| erp\_phi\_max | float32 | specifies the maximum longitude range for an ERP projection in units of degrees |
| erp\_theta\_min | float32 | specifies the minimum latitude range for an ERP projection in units of degrees |
| erp\_theta\_max | float32 | specifies the maximum latitude range for an ERP projection in units of degrees |
| } else if (view\_type == 1) { |  | perspective projection |
| perspective\_focal\_hor | float32 | specifies in luma samples position units the horizontal components of the focal of a perspective projection of the view with view index |
| perspective\_focal\_ver | float32 | specifies in luma samples position units the vertical components of the focal of a perspective projection of the view with view index |
| perspective\_principal\_point\_hor | float32 | specifies in luma sample positions the horizontal coordinates of the principal point of a perspective projection of the view |
| perspective\_principal\_point\_ver | float32 | specifies in luma sample positions the vertical coordinates of the principal point of a perspective projection of the view |
| } else if ( view\_type -== 2) { |  | orthographic projection |
| ortho\_height | float32 | specifies in scene units the vertical dimensions of the captured part of the volumetric frame |
| ortho\_width | float32 | specifies in scene units the horizontal dimensions of the captured part of the volumetric frame |
| } |  |  |
| quantization\_law | uint8 | specifies the type of depth quantization method of the view |
| if ( quantization\_law == 0) { |  |  |
| norm\_dis\_low | uint8 | specifies the normalized disparity of the lowest signalled geometry value |
| norm\_dis\_high | uint8 | specifies the normalized disparity of the highest signalled geometry value |
| } |  |  |
| depth\_occ\_threshold | uint8 | specifies the default occupancy threshold used in the occupancy value extraction process |
| pp\_root | bool | specifies whether the view has a parent in the pruning graph at the encoder stage |
| if (!pp\_root) { |  |  |
| pp\_num\_parents | uint8 | specifies the number of parents of the view in the pruning graph at the encoder stage |
| for ( int i = 0; i < pp\_num\_parents; i++) { |  |  |
| pp\_view\_parent\_idx | uint8 | specifies the index of the i-th parent view in the pruning graph at the encoder stage. |
| } |  |  |
| } |  |  |
| } |  |  |

### Processing Model

#### G.1.6.1 General

The Presentation Engine is equipped with a graphics processing unit (GPU). The loader in the Presentation Engine will parse the MPEG-I scene description file. If the loader supports the reconstruction of V3C objects and accepts the MPEG\_primitive\_V3C extension, then the loader in the presentation engine will process the MPEG\_primitive\_V3C extension for a mesh element that contains the extension. The presentation engine will then request the MAF to supply the decoded V3C data indicated by the extension in the associated buffers. The decoded V3C data provided by the properties specified by the MPEG\_primitive\_V3C extension are then loaded to the GPU memory.

An implementation (e.g., a shader implementation) is run on the decoded V3C data to generate the final 3D reconstructed object. The logic of 3D reconstruction is facilitated by using the V3C information such as atlas, geometry, and occupancy. The 3D object can be further textured using the texture information with different V3C attributes.

Since the MPEG\_primitive\_V3C extension is expressed at the mesh-level, a node referencing a mesh with the MPEG\_primitive\_V3C extension will position the object in the scene graph for rendering.

The transformation parameters in the V3C bitstream as defined in H.8.3.6.3.3 shall be ignored.

#### G.1.6.2 MIV support

MIV is a special case of the V3C representation in MPEG-I scene description as meshes. The MPEG-I scene description author will supply the viewing space boundaries in the accessor referred to by the “POSITION” attribute of a mesh. The viewing space boundaries are conveyed by the MIV bitstream. The texture of the MIV content is directly passed to the renderer based on different camera views in the viewing space. The information for the camera views is stored in the atlas property of the MPEG\_primitive\_V3C extension.

## MPEG\_sampler\_YCbCr extension

### General

A sampler-level extension is described to sample a video texture natively in parallel processing devices such as GPUs. This extension shall be present if the format of the referencing video texture is set to YCbCr.

A texture object in the textures array may use a sampler with the “MPEG\_sampler\_YCbCr” sampler extension to provide information to the Presentation Engine to sample the video texture when the texture format is a chroma format such as YCbCr.

### Semantics

Table G.11 provides a description of the properties defined in the MPEG\_sampler\_YCbCr sampler extension.

Table G.11 MPEG\_sampler\_YCbCr semantic

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Name** | **Type** | **Default** | **Usage** | **Description** |
| ycbcrModel | integer | 1 | O | Describes the color matrix for conversion between color models. The supported formats are defined by the VkSamplerYcbcrModelConversion enumeration in clause 13.1 of Vulkan 1.3. |
| ycbcrRange | integer | 0 | O | Describes whether the encoded values have headroom and foot room, or whether the encoding uses the full numerical range. |
| chromaFilter | integer | 0 | O | Describes the filter for chroma reconstruction. |
| components | array(integer) | [0,0,0,0] | O | Applies a swizzle to the [r,g,b,a] components based on [VkComponentSwizzle](https://registry.khronos.org/vulkan/specs/1.3-extensions/html/vkspec.html" \l "VkComponentSwizzle) enums prior to range expansion and color model conversion. If present, the array shall include 4 values, each of which corresponding to the r,g,b,a components in order of appearance. |
| xChromaOffset | integer | 0 | O | Describes the [sample location](https://registry.khronos.org/vulkan/specs/1.3-extensions/html/vkspec.html" \l "textures-chroma-reconstruction) associated with downsampled chroma components in the x dimension. xChromaOffset has no effect for formats in which chroma components are not downsampled horizontally. |
| yChromaOffset | integer | 0 | O | Describes the [sample location](https://registry.khronos.org/vulkan/specs/1.3-extensions/html/vkspec.html" \l "textures-chroma-reconstruction) associated with downsampled chroma components in the y dimension. yChromaOffset has no effect for formats in which the chroma components are not downsampled vertically. |

### Processing Model

The MPEG\_sampler\_YCbCr extension provides relevant configuration information for the native YCbCr device extensions or shader compiler to read and sample a YCbCr texture.

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