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| **Title** | **Description of EE13.47 on spherical coordinate geometry** |
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# Abstract

This document provides a description of G-PCC Exploration Experiment (EE) 13.47 on spherical coordinate geometry for predictive geometry coding.

# Introduction

The goal of EE13.47 is to investigate the predictive geometry angular coding method to encode/decode the spherical coordinate data that was proposed in m55361[1], m56809[2], and m57358[3].

In current G-PCC specification, only cartesian coordinates (x, y, z) is supported as the input/output format of geometry. For example, when use the angular mode on predictive geometry coding, input geometry with cartesian coordinates (x, y, z) is converted to spherical coordinates (r, j, i) and the spherical coordinates data is encoded.

However, the sensor may output in the data format of the spherical coordinate system (ex. Velodyne LiDAR) that include vector of the reflectance per angle of sensor.

In m55361 and m55993, new predictive geometry angular coding method to encode/decode the spherical coordinate data was proposed.

# Proposed Encoder/Decoder

## Encoder

Figure 1 shows a diagram of the encoder for predictive geometry coding.

Currently predictive geometry coding support two coding mode (angular mode on / off) that encode the cartesian coordinate input data. We proposed to add the new method that can encode the spherical coordinate input data with angular mode with no additional process.

This new method:

Point1: can input spherical coordinate data directly.

Point2: can quantize the residual even when no conversion error (residual 2).

Point3: no additional process (select the existing function by 1bit flag).

### Input format: Cartesian coordinate, Angular mode: OFF

When encoding the cartesian coordinate data with the Cartesian coordinate system (angular mode = OFF), prediction, residual generation, quantization, and entropy coding are processed.

### Input format: Cartesian coordinate, Angular mode: ON

When encoding the cartesian coordinate data with the Spherical coordinate system (angular mode = ON), the input data is converted from cartesian coordinate to spherical coordinate. Residual by predicting is encoded with spherical coordinate as Residual 1, and the residual due to coordinate transformation is quantized and encoded as Residual 2.

### Input format: Spherical coordinate, Angular mode: ON [NEW]

When encoding the spherical data with the Spherical coordinate system (angular mode = ON), the input data can be encoded with spherical coordinate system (angular mode = ON) directly.

The process of coordinate conversion and Residual 2 encoding are not necessary compared to encoding with the Cartesian coordinate system. Instead of quantization of Residual 2, Residual 1 is quantized.

Each function to achieve this new encoding method is already included in the conventional encoder, so it can be easily achieved by switching the existing process. Existing azimuth scaling can be used for quantizing Residual 1.

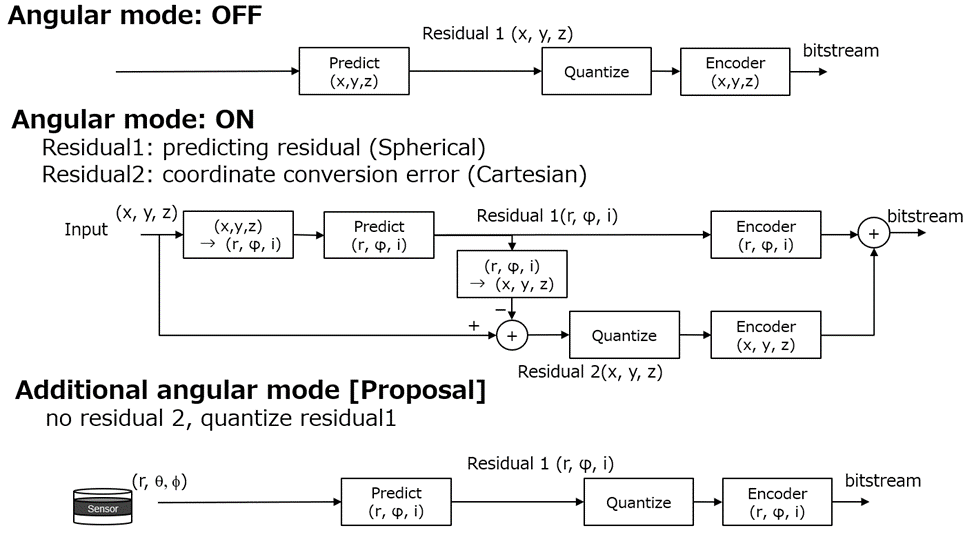


Figure 1 A diagram of the Encoder

## Decoder

Figure 2 shows a diagram of the decoder. The process of the decoder is opposite of the encoder process.

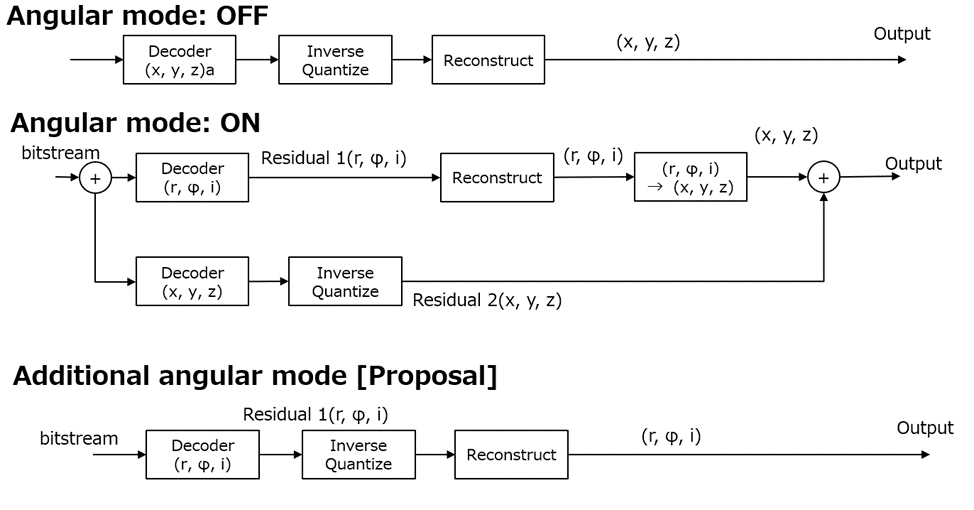


Figure 2 A diagram of the decoder

# geom\_coordinate\_conversion\_flag

Introduces a new flag **geom\_coordinate\_conversion\_flag** in order to switch the coordinate conversion processing is used or not. In combination with **angular\_mode\_enabled\_flag**, it can be switched between 3 modes.

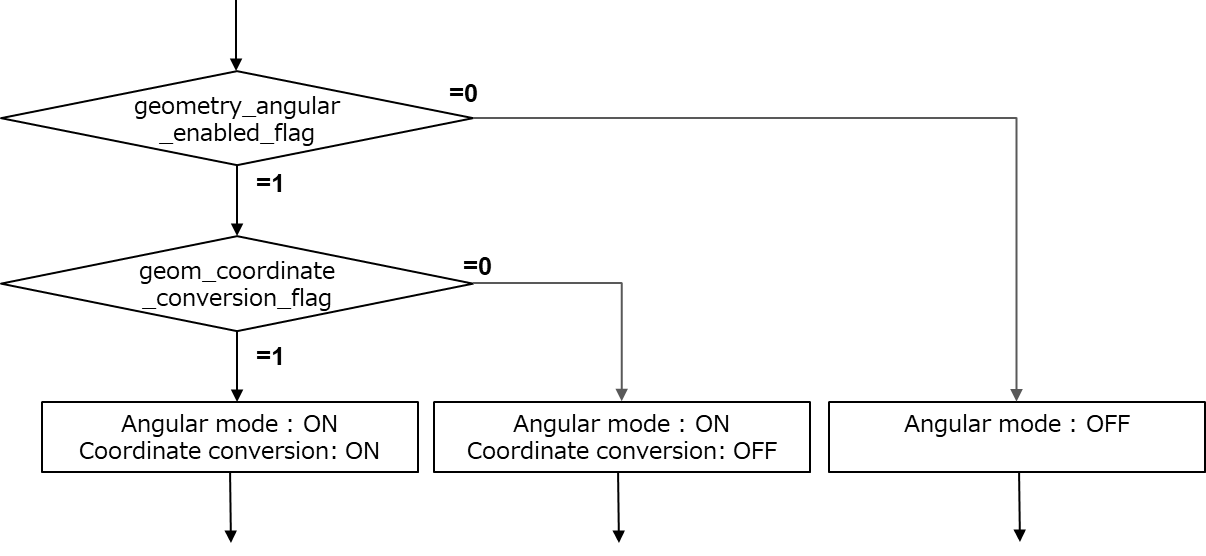


Figure 3 Decoding process

# Experimental description

## Mandates

The concept for the proposed method was agreed in MPEG134 meeting and the software [4] and specification draft [3] were provided in MPEG135.

Mandates for EE13.47 is to investigate the decoding process and specification based on G-PCC v2 WD. In particular, mandate for new EE is to investigate the interaction of the coding tools and the coordinate system and do experiment on the latest TMC13 software.

## Participants

| **Name** | **Company** | **E-mail address** | **Type** |
| --- | --- | --- | --- |
| Noritaka Iguchi | Panasonic | iguchi.noritaka@jp.panasonic.com | Proponent |
|  |  |  | Cross checker |

## EE13.47 Coordinators

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# Timeline:

* **2022-08-05**: release the EE description
* **2022-10-05**: Expected delivery date of source codes and results for crosscheck
* **2022-10-12**: Expected delivery date of crosscheck results
* **2022-10-19**: Deadline of upload the document to MPEG

# References

1. [G-PCC][New] Predictive geometry angular mode using spherical LiDAR data input, ISO/IEC JTC1/SC29/WG7 MPEG2020/m55361 October 2020, Online.
2. EE13.47 report on spherical coordinate geometry, ISO/IEC JTC 1/SC 29/WG 7 m56809, April 2021, Online.
3. EE13.47 report on spherical coordinate geometry, ISO/IEC JTC 1/SC 29/WG 7 m58051, October 2021, Online.
4. http://mpegx.int-evry.fr/software/MPEG/PCC/CE/mpeg-pcc-tmc13/-/tree/mpeg135/mtg/m54258-ee1347\_SphericalCoordGeom